Properties:

- A^{-1} exists implies $(A^T)^{-1} = (A^{-1})^T$.
- A, B, both invertible, implies $(AB)^{-1} = B^{-1}A^{-1}$.
- A^{-1} exists means $(A^{-1})^{-1} = A$.
- A invertible then cA is too, for $c \in \mathbb{R} \neq 0$. $(cA)^{-1} = \frac{A^{-1}}{c}$.
- I is invertible. $I^{-1} = I$.
- A invertible then A^k is invertible, $(A^k)^{-1} = (A^{-1})^k = A^{-k}$ (use $A^0 = I$).
- If A is invertible, its inverse is unique.

Now take a look at what this means for a linear system:

 $\implies A^{-1}Ax = A^{-1}b \implies x = A^{-1}b.$ $A\mathbf{x} = \mathbf{b}, \quad A \text{ invertible}$

Having an invertible A on the left hand side means you can get the solution that way (usually not worth the effort, just solve it), so

- You ALWAYS get a solution (always consistent).

This is primarily of value when one has to calculate many rotations of the form $A\mathbf{x} = \mathbf{b}$. Each can then be solved with a mere multiplication, writing else.

smaller than 3×3

For a
$$1 \times 1$$
, $[a]^{-1} = \left[\frac{1}{a}\right]$. Sorry, couldn't resist.

For a 2 × 2:
$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$
.

Example:

$$\begin{bmatrix} 2 & -1 \\ 4 & -3 \end{bmatrix}^{-1} = \frac{1}{-6+4} \begin{bmatrix} -3 & 1 \\ -4 & 2 \end{bmatrix} = \begin{bmatrix} \frac{3}{2} & -\frac{1}{2} \\ 2 & -1 \end{bmatrix}.$$

Once you're dealing with a bigger matrix than that, you have to row reduce. For A, an $n \times n$ matrix, simply solve the linear system [A|I], row reduce the left down to I and the right will be A^{-1} .