

Lemma 1.28 There is a 1-1 correspondence between any two right cosets of H in G .

Theorem 1.29 Lagrange's Theorem: If G is a finite group and H is a subgroup of G , then $O(H)$ is the divisor of $O(G)$, converse of the Lagrange's theorem need not be true.

Example 1.30 1. Let $G = \{1, -1, i, -i\}$, $H = \{i, -1\}$. Then $O(H)/O(G)$ but H is not a subgroup of G .

2. Let $G = S_3 = \{e, p_1, p_2, p_3, p_4, p_5\}$, $H = \{p_1, p_2\}$. Then $O(H)/O(G)$ but H is not a subgroup of G .

Definition 1.31 Index: If H is a subgroup of G , the index of H in G is the number of distinct right cosets of H in G . It is denoted by $i_G(H)$.

Remark 1.32 $i_G(H) = \frac{O(G)}{O(H)}$

Example 1.33 Let $G = \{Z_{12}, \oplus_{12}\}$; $H = \{0, 4, 8\}$. Then $i_G(H) = 4 = 12/3 = \frac{O(G)}{O(H)}$

Definition 1.34 If G is a group and $a \in G$. The order of a (period of a) is the least positive integer m such that $a^m = e$. If no such integer exists, we say that a is of infinite order.

Example 1.35 Let $G = \{1, -1, i, -i\}$

$$1. a = -1 \Rightarrow a^2 = (-1)^2 = 1 \Rightarrow O(a) = 2$$

$$2. a = i \Rightarrow a^4 = i^4 = 1 \Rightarrow O(a) = 4.$$

Example 1.36 In $(Z_{12}, \oplus)$, $O([1]) \in Z_{12}$

Now, $O([2]) = 6 \{ [2] + [2] + [2] + [2] + [2] + [2] = 0 \}$

$$O([3]) = 4; O([6]) = 2.$$

Example 1.37 Let $(Z, +)$, $e=0$. Then $1 \in Z$ is of infinite order. **Corollary 1.38** If G is

a finite group and $a \in G$, then $O(a)$ divides $O(G)$. **Corollary 1.39** If G is finite and

$a \in G$, then $a^{O(G)} = e$.

Definition 1.40 Euler function $\phi(n)$: $\phi(1) = 1$, $\phi(n)$ = number of positive integers less than n and relatively prime to n for $n > 1$.

$\phi(8) = 4$ ($\because 1, 3, 5, 7$ are relatively prime to 8), $\phi(5) = 4$, $\phi(7) = 6$, $\phi(10) =$

4, $\phi(15) = 8$.

Example 1.94

$$\begin{array}{c}
 - \\
 \begin{array}{cccc}
 1 & 2 & 3 & 4 \\
 2 & 1 & 4 & 3
 \end{array}
 \end{array}
 \begin{array}{c}
 \Sigma \\
 \\
 \Sigma
 \end{array}
 = (1\ 2)(3\ 4) = \text{even permutation}$$

$$\begin{array}{c}
 - \\
 \begin{array}{ccccc}
 1 & 2 & 3 & 4 & 5 \\
 2 & 1 & 3 & 5 & 4
 \end{array}
 \end{array}
 \begin{array}{c}
 \Sigma \\
 \\
 \Sigma
 \end{array}
 = (1\ 2)(3\ 4\ 5) = \text{odd permutation}$$

Result 1.95 A permutation can be written either as a product of an even number of transpositions or as a product of an odd number of transpositions and not both.

Proof: Let $\vartheta \in S_n$

Suppose ϑ can be written as a product of X transpositions in one way and can be written as a product of Y transpositions in another way. Consider a polynomial in variables $x_1, x_2, \dots, x_n$ which are the elements of S .

$$P(x_1, x_2, \dots, x_n) = \prod_{i < j} (x_i - x_j).$$

Let $\vartheta \in S_n$ be a permutation on n -symbols $1, 2, \dots, n$. Let ϑ be act on $P(x_1, x_2, \dots, x_n)$ by

$$\vartheta : P(x_1, x_2, \dots, x_n) = \prod_{i < j} (x_i - x_j) \rightarrow \prod_{i < j} (x_{\vartheta(i)} - x_{\vartheta(j)}).$$

It is clear that $\vartheta : P(x_1, x_2, \dots, x_n) \rightarrow \pm P(x_1, x_2, \dots, x_n)$. For example, consider $\vartheta = (1\ 3\ 4)(2\ 5) \in S_5$. Then $P(x_1, x_2, \dots, x_5) = (x_1 - x_2)(x_1 - x_3)(x_1 - x_4)(x_1 - x_5)(x_2 - x_3)(x_2 - x_4)(x_2 - x_5)(x_3 - x_4)(x_3 - x_5)(x_4 - x_5)$; $\vartheta(P(x_1, x_2, \dots, x_5)) = (x_3 - x_5)(x_3 - x_4)(x_3 - x_2)(x_3 - x_1)(x_5 - x_2)(x_5 - x_4)(x_5 - x_1)(x_4 - x_2)(x_4 - x_1)(x_4 - x_3)(x_2 - x_1)(x_2 - x_3)(x_2 - x_4)(x_2 - x_5)(x_3 - x_4)(x_3 - x_5)(x_4 - x_5) = -P(x_1, x_2, \dots, x_5)$.

Suppose $\vartheta = (1\ 2) \in S_2$; $P(x_1, x_2) = (x_1 - x_2)$; $\vartheta(P(x_1, x_2)) = (x_2 - x_1) = -(x_1 - x_2) = -P(x_1, x_2)$. (i.e) The effect of a transposition on P is to change the sign of P . Now the operation by a transposition (rs) where $r < s$ has the following effects on P .

- (i) Any factor of P which contains neither the suffix r nor s remains unchanged
- (ii) The single factor $(x_r - x_s)$ changes its sign by replacing r by s and s by r
- (iii) The remaining factor which contain either the suffix r (or) s but not both can be grouped into the following 3 types of products.

$$(a) [(x_1 - x_r)(x_1 - x_s)][(x_2 - x_r)(x_2 - x_s)] \dots [(x_{r-1} - x_r)(x_{r-1} - x_s)]$$

$$(b) [(x_r - x_{r+1})(x_{r+1} - x_s)][(x_r - x_{r+2})(x_{r+2} - x_s)] \dots [(x_r - x_{s-1})(x_{s-1} - x_s)]$$

$$(c) [(x_r - x_{s+1})(x_{s+1} - x_s)][(x_r - x_{s+2})(x_{s+2} - x_s)] \dots [(x_r - x_n)(x_s - x_n)]$$

On replacing r by s and s by r , the signs of all types of products do not change. Hence effect of the transposition (rs) on P is to change the sign of

2. UNIT II

Another Counting Principle

Definition 2.1 If $a, b \in G$, then b is said to be a conjugate of a in G if there exists an element $c \in G$ such that $b = c^{-1}ac$. We shall write this conjugate relation as $a \sim b$. (i.e.) $a \sim b \Rightarrow b$ is conjugate to $a \Rightarrow b = c^{-1}ac, c \in G$.

Lemma 2.2 Conjugation is an equivalence relation on G .

Proof: (i) $\sim$ is reflexive:

Let $a \in G$, then $a = a^{-1}ae, a \in G \Rightarrow a \sim a \forall a \in G. \therefore \sim$ is reflexive.

(ii) $\sim$ is symmetric:

Suppose, $a \sim b \Rightarrow b = c^{-1}ac, c \in G. \Rightarrow a = c b c^{-1} = (c^{-1})^{-1}b(c^{-1}) = x^{-1}bx, x = c^{-1} \in G \Rightarrow b \sim a. \sim$ is symmetric. (iii) $\sim$ is

transitive:

Suppose $a \sim b$ and $b \sim c$. Then $a \sim b \Rightarrow b = x^{-1}ax, x \in G; b \sim c \Rightarrow c = y^{-1}by, y \in G$. Now, $c = y^{-1}by = y^{-1}(x^{-1}ax)y = (y^{-1}x^{-1})a(xy) = (xy)^{-1}a(xy) = z^{-1}az, z = xy \in G \Rightarrow a \sim c. \therefore \sim$ is transitive.

Hence, $\sim$ is an equivalence relation.

Definition 2.3 For any $a \in G$, let $C(a) = \{x \in G \mid x \sim a\}$, $C(a)$ is the equivalence class of a in G , under the relation $\sim$. It is usually called the conjugate class of $a \in G$.

Remark 2.4 $C(a) = \{x \in G \mid x \sim a\} = \{x \in G \mid x = y^{-1}ay, y \in G\} = \{y^{-1}ay \mid y \in G\}$. It consists of the set of all distinct elements of the form $x^{-1}ax$ as x ranges over G . Suppose the number of elements in $C(a)$ is denoted by Ca . Since the union of all distinct conjugate classes is G .

$$G = C(a_1) \cup C(a_2) \cup \dots \cup C(a_n)$$

$$O(G) = Ca_1 + Ca_2 + \dots + Ca_n = \sum_{a \in G} Ca_i$$

Where the summation runs over each element a in each conjugate classes.

Definition 2.5 If $a \in G$, $N(a)$, normaliser of a is defined as $\{x \in G \mid ax = xa\}$

Example 2.6 (i) $G = \{1, -1, i, -i\}$. When $a = 1, N(a) = N(1) = \{1, -1, i, -i\} = G$; When $a = -1, N(-1) = G$.

(ii) $G = \{Z_5, \oplus_5\}$. $a = [2], N(a) = N([2]) = \{[0], [1], [2], [3], [4]\}$

(iii) $G = S_3 = \{e, \varphi, \psi, \varphi \cdot \psi, \psi \cdot \varphi, \psi^2\}$. $N(\varphi) = \{e, \varphi\}$; $N(\psi) = \{e, \psi, \psi^2\}$; $N(\psi^2) = \{e, \psi^2, \psi\}$.

Lemma 2.7 $N(a)$ is a subgroup of G .

Proof: Let $x, y \in N(a) \Rightarrow ax = xa$ and $ay = ya$ (1)

Now, $a(xy) = (ax)y = (xa)y = x(ay) = x(ya) = (xy)a \Rightarrow$

$xy \in N(a) \forall x, y \in N(a)$ (2)

Suppose $x \in N(a) \Rightarrow ax = xa \Rightarrow x^{-1}a = ax^{-1}$ [By premultiply and post multiply by x^{-1}] $\Rightarrow x^{-1} \in N(a)$ (3)

By (2) and (3), $N(a)$ is a subgroup of G .

Calculation for $C(a)$:

Let $G = S_3 = \{e, \phi, \psi, \phi \cdot \psi, \psi \cdot \phi, \psi^2\}$. $C(\phi) = \{x^{-1}\phi x \mid x \in S_3\} =$

$\{e^{-1}\phi e, \phi^{-1}\phi\phi, \psi^{-1}\phi\psi, (\phi \cdot \psi)^{-1}\phi(\phi \cdot \psi), (\psi \cdot \phi)^{-1}\phi(\psi \cdot \phi), (\psi^2)^{-1}\phi\psi^2\}$

$C(1, 2) = \{e^{-1}(1, 2)e, (1, 2)^{-1}(1, 2)(1, 2), \psi^{-1}(1, 2)\psi, (\phi \cdot \psi)^{-1}(1, 2)(\phi \cdot \psi), (\psi \cdot \phi)^{-1}(1, 2)(\psi \cdot \phi), (\psi^2)^{-1}(1, 2)\psi^2\} = \{(1, 2, 3)(1, 2)(1, 2, 3), (1, 2)(1, 2)(1, 2),$

$(1, 3, 2)(1, 2)(1, 3, 2), (1, 3)(1, 2)(1, 3), (2, 3)(1, 2)(2, 3), (2, 3, 1)(1, 2)(2, 3, 1)\} =$

$\{(1, 2), (1, 2), (2, 3)\} \therefore C(\phi) = \{\phi, \phi \cdot \psi, \psi \cdot \phi\}$

$C = O(C(1, 2)) = 3 \cdot \frac{O(G)}{O(N(a))} = 3 \cdot \frac{O(S_3)}{O(N(1, 2))} = 3 \cdot \frac{6}{2} = 3 \therefore C = \frac{O(G)}{O(N(a))}$

(1,2)

$O(N(1,2))$

3

(1,2)

$O(N(1,2))$

Theorem 2.8 If G is a finite group, then $C_a = \frac{O(G)}{O(N(a))}$; In other words, the number of elements conjugate to a in G is the index of $N(a)$ in G . **Proof:** We shall show that two elements in the same right coset of $N(a)$ in G give the same conjugate of a in G , where as two elements in different cosets of $N(a)$ in G gives rise to different conjugate of a in G . In this way we shall have a 1-1 correspondence between conjugate of a in G and the right cosets of $N(a)$ in G . Suppose $x, y \in G$ are in the same right coset of $N(a)$ in G . Then $y = nx$ where $n \in N(a)$, $[\because y \in N(a)x, y = nx] \Rightarrow y^{-1} = (nx)^{-1} = x^{-1}n^{-1}$; $y^{-1}ay = x^{-1}n^{-1}ay = x^{-1}(n^{-1}an)x = x^{-1}ax$. Hence, x and y result in the same conjugate of a in G . In other words if x and y are in different right cosets of $N(a)$ in G .

Claim that $x^{-1}ax \neq y^{-1}ay$. Suppose not $x^{-1}ax = y^{-1}ay$. Premultiply by y and post multiply by x^{-1} , then $yx^{-1}axx^{-1} = y(y^{-1}ay)x^{-1} \Rightarrow yx^{-1}a = ayx^{-1} \Rightarrow (yx^{-1})a = a(yx^{-1}) \Rightarrow yx^{-1} \in N(a)$ $[\because ab^{-1} \in H \Leftrightarrow Ha = Hb] \Rightarrow N(a) \cdot y = N(a) \cdot x \Rightarrow x$ and y to be in the same right cosets of $N(a)$ in $G \Rightarrow$ to the fact that x and y are in different right coset of $N(a)$ in G .

$\therefore x^{-1}ax \neq y^{-1}ay$. Hence x and y yield the different conjugate of a in G if they are in different right cosets of $N(a)$ in G . $\therefore$ The number of elements conjugate to a in G = number of distinct right cosets of $N(a)$ in G . (i.e.) the number of elements conjugate to a in G = the index of normaliser of a in G . (i.e.) $C_a = \frac{O(G)}{O(N(a))}$. Hence, the theorem.

$O(N(a))$

Corollary 2.9

$$O(G) = \sum \frac{O(G)}{O(N(a))}, \forall a \in G$$

+ is well define:

Suppose $[a, b] = [a', b']$ and $[c, d] = [c', d']$, then $[a, b] + [c, d] = [a', b'] + [c', d']$. To Prove: $[ad+bc, bd] = [a'd'+b'c', b'd']$. It is enough to prove $(ad+bc)b'd' = bd(a'd' + b'c')$. Now, $[a, b] = [a', b'] \Rightarrow ab' = ba'$ (1) and $[c, d] = [c', d'] \Rightarrow cd' = dc'$ (2)

$$\begin{aligned}(ad+bc)b'd' &= adb'd' + bcb'd' \\ &= ab'dd' + bb'cd' \\ &= ba'dd' + bb'dc \\ &= bd(a'd' + b'c')\end{aligned}$$

$\therefore +$ is well defined.

+ is closed:

Let $[a, b], [c, d] \in F$. Then D is an integral domain, $bdf = 0$. Now, $[a, b] + [c, d] = [ad + bc, bd] \in F [\because bdf = 0]$. $\therefore +$ is closed.

+ is associative:

$$\begin{aligned}([a, b] + [c, d]) + (e, f) &= [ad + bc, bd] + (e, f) \\ &= [(ad + bc)f + (bd)e, (bd)f] \\ &= [adf + bcf + bde, bdf] \\ &= [adf + (bcf + bde), bdf] \\ &= [a(df + bcf + bde), bdf] \\ &= [a(df + bcf + bde), bdf] \\ &= [a, b] + [cf + de, df] \\ &= [a, b] + ([c, d] + [e, f])\end{aligned}$$

$\therefore +$ is associative.

Additive identity:

$[0, b] \in F$ acts as zero element for this addition. For $[a, b] + [0, b] = [ab + 0, b^2] = [ab, b^2] = [a, b]$.

Additive inverse:

$[-a, b]$ acts as a additive inverse of $[a, b]$. For $[-a, b] + [a, b] = [-ab + ba, b^2] = [0, b^2]$.

+ is commutative:

$[a, b] + [c, d] = [ad+bc, bd] = [bc+ad, bd] = [cb+da, bd] = [c, d] + [a, b]$ $[a, b] + [c, d] \in F$.

$\therefore +$ is commutative.

$\therefore (F, +)$ is an abelian group.

+ is well defined:

Suppose $[a, b] = [a', b']$ and $[c, d] = [c', d']$. To Prove $[a, b] + [c, d] = [a', b'] + [c', d']$ (i.e.) $[ac, bd] = [a'c', b'd']$. It is enough to prove that $(ac)(b'd') =$

$\frac{d}{m}\lambda(x)$, where $d = (c_0, c_1, c_2, \dots, c_n)$, $\lambda(x)$ is primitive and d and m are integers.

Similarly $v(x) = \frac{d_1}{m_1}l_1(x)$, where d_1 and m_1 are integer and $l_1(x)$ is

primitive. $\therefore f(x) = u(x) \cdot v(x) = \frac{m_1 d}{m} \cdot \frac{d}{m_1} \cdot \lambda(x)l_1(x) = \frac{\lambda(x)}{b}l_1(x) \dots \dots \dots (2)$

where $a = dd_1$ and $b = mm_1$ are integers $\Rightarrow bf(x) = a\lambda(x)l_1(x) \dots \dots \dots (3)$

$\Rightarrow c(bf(x)) = c(a\lambda(x)l_1(x)) \Rightarrow bc(f(x)) = ac(\lambda(x)l_1(x)) \Rightarrow b = a \dots \dots \dots (4)$

[$\because f(x), l_1(x), \lambda(x)$ are primitive, their content is 1]. From (2) and (4), $f(x) = \lambda(x)l_1(x)$. $\therefore f(x)$ can be factored as a product of two polynomial having two integer coefficient. [$\lambda(x)$ and $l_1(x)$ are polynomial having integer coefficient]. Hence the theorem.

Corollary 3.68 *If an integer monic polynomial factors as the product of two non-constant polynomials having rational coefficients then it factors as the product of two integer monic polynomials.*

Proof: $f(x)$ is an integer monic polynomial and factored as a product of two non-constant polynomials having rational coefficients. (i.e.) $f(x)$ is a primitive polynomial factored as the product of two polynomial having rational coefficients. By Theorem 3.67 $f(x)$ can be factored as product of two polynomials having integer coefficients. Let $f(x) = p(x) \cdot r(x)$, where $p(x), r(x)$ are polynomial with integer coefficient. Let $p(x) = a_0 + a_1x + a_2x^2 + \dots + a_nx^n$ and $r(x) = b_0 + b_1x + b_2x^2 + \dots + b_mx^m$, where a_i 's and b_j 's

are integers. $\because f(x)$ is monic, leading coefficient of $f(x)$ is 1. Then leading coefficient of $p(x) \cdot r(x) = 1 \Rightarrow a_n = b_m = 1 \Rightarrow$ either $a_n = b_m = 1$ (or) $a_n = b_m = -1$.

$\therefore$ In either case, $p(x), r(x)$ are integer monic polynomials. Hence $f(x)$ can be factored as the product of two integer monic polynomials.

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Page 48 of 109

Example 4.27 In the vector space $F^{(n)} = V_n(F) = \{(\alpha_1, \alpha_2, \dots, \alpha_n)\}$. Then the vector space $S = \{e_1, e_2, \dots, e_n\}$ where $e_1 = \{1, 0, \dots, 0\}$; $e_2 = \{0, 1, 0, \dots, 0\}$; $\dots$; $e_n = \{0, 0, \dots, 1\}$ is linearly independent. Let $\lambda_1, \lambda_2, \dots, \lambda_n \in F$. Then $\lambda_1 e_1 + \lambda_2 e_2 + \dots + \lambda_n e_n = 0 \Rightarrow \lambda_1(1, 0, \dots, 0) + \lambda_2(0, 1, \dots, 0) + \dots + \lambda_n(0, 0, \dots, 1) = 0 \Rightarrow (\lambda_1, 0, \dots, 0) + (0, \lambda_2, \dots, 0) + (0, 0, \dots, \lambda_n) = 0 \Rightarrow (\lambda_1, \lambda_2, \dots, \lambda_n) = 0 \Rightarrow \lambda_1 = 0, \lambda_2 = 0, \dots, \lambda_n = 0$.

Remark 4.28 If the set of vector $S = \{v_1, v_2, \dots, v_n\}$ is linearly independent then none of the vector $v_1, v_2, \dots, v_n$ be $\vec{0}$.

Example 4.29 Show that the set $S = \{(1, 2, 4), (1, 0, 0), (0, 1, 0), (0, 0, 1)\}$ is a linearly dependent subset of vector space $R^{(3)}$ where R is the field of Real numbers.

Solution: Let $\lambda_1 = 1, \lambda_2 = -1, \lambda_3 = -2, \lambda_4 = -4$. Then $1(1, 2, 4) + (-1)(1, 0, 0) + (-2)(0, 1, 0) + (-4)(0, 0, 1) = (1, 2, 4) + (-1, 0, 0) + (0, -2, 0) + (0, 0, -4) = (0, 0, 0)$. $\therefore$ Given set is linearly dependent.

Lemma 4.30 If $v_1, v_2, \dots, v_n$ are linearly independent then every element in their linear span has a unique representation in the form, $\lambda_1 v_1 + \lambda_2 v_2 + \dots + \lambda_n v_n$ with $\lambda_i \in F$.

Result 4.31 If $v_1, v_2, \dots, v_n \in V$ then either they are linearly independent or some v_k is the linear combination of the preceding one's. If V is a finite dimensional vector space then it contains a finite set $v_1, v_2, \dots, v_n$ of linearly independent elements whose linear span is V .

Definition 4.32 Basis: A subset S of a vector space V is called a basis of V if S consists of linearly independent elements and $V = L(S)$. Let set S consisting of vectors $e_1 = (1, 0, 0), e_2 = (0, 1, 0), e_3 = (0, 0, 1)$ is a basis of $F^{(3)}$.

- Result 4.33**
1. If V is a finite dimensional vector space and if $v_1, v_2, \dots, v_m$ span V then some subsets of $v_1, v_2, \dots, v_m$ forms a basis of V .
 2. If $v_1, v_2, \dots, v_m$ is a basis of V over F if $w_1, w_2, \dots, w_m$ in V are linearly independent over F then $m \leq n$.
 3. If V be a finite dimensional vector space over F then any two basis of V have the same number of elements. For example, $S_1 = \{(1, 0, 0), (0, 1, 0), (0, 1, 1)\}$ and $S_2 = \{(1, 0, 0), (1, 1, 0), (1, 1, 1)\}$ are two basis of the vector space $F_{(3)}$.
 4. $F^{(n)} \cong F^{(m)}$ iff $n = m$.
 5. If V be a finite dimensional vector space over a field F then $V \cong F^{(n)}$ for a unique integer n , infact n is the number of elements in any basis V over F .

$$2. \dim(A(W)) = \dim(V) - \dim(W).$$

$$3. \hat{V}/A(W) = \hat{W}.$$

$$4. A(A(W)) = W.$$

Linear Transformation:

We know that $\text{Hom}(V, W)$, the set of all vector space homomorphisms of V into W is a vector space over the field F . In this section we are very much interested on $\text{Hom}(V, V)$.

Definition 4.45 An associative ring A is said to be an algebra over F if A is a vector space over a field F such that $a, b \in A$ and $\alpha \in F$, $\alpha(ab) = (\alpha a)b$.

Remark 4.46 Every algebra A over a field F is a vector space over a field F . Is the converse true?

Result 4.47 $\text{Hom}(V, V)$ is an algebra over F .

Proof: Let $T_1, T_2 \in \text{Hom}(V, V)$. Define $+$ and $\cdot$ as follows, $T_1 + T_2 : V \rightarrow V$ by $v(T_1 + T_2) = vT_1 + vT_2$ and $T_1 \cdot T_2 : V \rightarrow V$ by $v(T_1 \cdot T_2) = (vT_1)T_2 \forall v \in V$. We shall first prove that $\text{Hom}(V, V)$ is a ring. Let $\alpha, \beta \in F$ and $v_1, v_2 \in V$,

$$\begin{aligned} (\alpha v_1 + \beta v_2)(T_1 + T_2) &= (\alpha v_1 + \beta v_2)T_1 + (\alpha v_1 + \beta v_2)T_2 \\ &= (\alpha v_1)T_1 + (\beta v_2)T_1 + (\alpha v_1)T_2 + (\beta v_2)T_2 \\ &= \alpha(v_1T_1) + \beta(v_2T_1) + \alpha(v_1T_2) + \beta(v_2T_2) \\ &= \alpha(v_1T_1 + v_1T_2) + \beta(v_2T_1 + v_2T_2) \\ &= \alpha(v_1(T_1 + T_2)) + \beta(v_2(T_1 + T_2)) \end{aligned}$$

$\therefore T_1 + T_2 \in \text{Hom}(V, V) \Rightarrow +$ is closed.

Let $T_1, T_2, T_3 \in \text{Hom}(V, V)$. Then $T_1(T_2 + T_3) = (T_1 + T_2)T_3 \forall T_1, T_2, T_3 \in \text{Hom}(V, V) \Rightarrow +$ is Associative.

$0 : V \rightarrow V$ defined by $v_0 = 0 \forall v \in V$ serve as additive identity element. For $0 + T_1 = T_1 + 0 = T_1 \forall T_1 \in \text{Hom}(V, V)$.

Inverse of T_1 is $-T_1$ defined by, $v(-T_1) = -(vT_1) \forall v \in V$. Since $T_1 + (-T_1) = (-T_1 + T_1) = 0$ for $v(T_1 + (-T_1)) = vT_1 + v(-T_1) = vT_1 + (-vT_1) = 0$. Similarly $v(-T_1 + T_1) = 0 \Rightarrow T_1 + (-T_1) = (-T_1) + T_1 = 0$.

$v(T_1 + T_2) = vT_1 + vT_2$ [$vT_1, vT_2 \in V$ and $(V, +)$ is abelian] $= vT_2 + vT_1 =$

$v(T_2 + T_1) \Rightarrow T_1 + T_2 = T_2 + T_1. \therefore +$ is commutative. Hence

$(\text{Hom}(V, V), +)$ is abelian group. Now,

$$\begin{aligned} (v_1 + v_2)(T_1 \cdot T_2) &= ((v_1 + v_2)T_1) \cdot T_2 \\ &= (v_1T_1 + v_2T_1) \cdot T_2 \\ &= (v_1T_1)T_2 + (v_2T_1)T_2 \\ &= v_1(T_1 \cdot T_2) + v_2(T_1 \cdot T_2) \end{aligned}$$

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Page 55 of 109

Remark 4.64 If V is finite dimensional over F then an element in $A(V)$ which is right invertible is invertible.

Theorem 4.65 If V is finite dimensional over F , then $T \in A(V)$ is invertible iff the constant terms of the minimal polynomial for T is not zero.

Proof: Let $p(x) = \alpha_0 + \alpha_1 x + \alpha_2 x^2 + \dots + \alpha_k x^k$ be the minimal polynomial for T . Assume that $\alpha_0 \neq 0$ and $p(T) = 0$. To prove: T is invertible. Since $p(x)$ is a minimal polynomial for T .

$$p(T) = 0 \Rightarrow \alpha_0 + \alpha_1 T + \dots + \alpha_k T^k = 0 \dots\dots\dots (1)$$

$$\alpha_0 = -(\alpha_1 T + \dots + \alpha_k T^k)$$

$$\alpha_0^{-1} = -(\alpha_1 T + \dots + \alpha_k T^{k-1}) T^{-1} \alpha = T$$

$$(-\alpha_0 - \alpha_1 T + \dots - \alpha_k T^{k-1})$$

$$\Rightarrow 1 = T \left(\frac{1}{\alpha_0} (-\alpha_0 - \alpha_1 T - \dots - \alpha_k T^{k-1}) \right)$$

$$1 = T \left(-\frac{\alpha_0^{-1}}{\alpha_0} (\alpha_0 + \alpha_1 T + \dots + \alpha_k T^{k-1}) \right)$$

Let $S = -\frac{1}{\alpha_0}(\alpha_1 + \alpha_2 T + \dots + \alpha_k T^{k-1})$. Clearly, $S \neq 0$ and $TS = 1$. Similarly $ST = 1$. Thus $ST = TS = 1$. T is invertible. Conversely, Suppose that T is invertible. To prove: $\alpha_0 \neq 0$. Suppose not, $\alpha_0 = 0$. From (1),

$$\alpha_1 T + \alpha_2 T^2 + \dots + \alpha_k T^k = 0 \quad (\alpha_0 = 0)$$

$$(\alpha_1 T + \alpha_2 T^2 + \dots + \alpha_k T^{k-1}) T = 0.$$

Since T is invertible, T^{-1} exist. Multiplying the above relation by T^{-1} ,

$$\Rightarrow ((\alpha_1 T + \alpha_2 T^2 + \dots + \alpha_k T^k) T^{-1}) T^{-1} = 0 T^{-1} = 0$$

$$\Rightarrow \alpha_1 T + \alpha_2 T^2 + \dots + \alpha_k T^{k-1} = 0 \dots\dots\dots (2)$$

Let $q(x) = \alpha_1 x + \dots + \alpha_k x^{k-1}$. By (2), $q(T) = 0$. (i.e.) T satisfy the polynomial $q(x)$ of degree $k-1$, which is a contradiction to the degree of minimal polynomial for T , which is $k \Rightarrow$ shows that $\alpha_0 \neq 0$.

Corollary 4.66 If V is finite dimensional over F and if $T \in A(V)$ is invertible then T^{-1} is a polynomial expression in T over F .

Proof: Let $p(x) = \alpha_0 + \alpha_1 x + \alpha_2 x^2 + \dots + \alpha_k x^k$ with $\alpha_k \neq 0$ be the minimal

polynomial of T .

$$\begin{aligned}
 p(T) = 0 &\Rightarrow \alpha_0 + \alpha_1 T + \alpha_2 T^2 + \dots + \alpha_k T^k = 0 \\
 \Rightarrow \alpha_0 &= -(\alpha_1 T + \alpha_2 T^2 + \dots + \alpha_k T^k) \\
 \alpha_0 &= (-\alpha_1)T + (-\alpha_2)T^2 + \dots + (-\alpha_k)T^k \\
 1 &= \left(-\frac{\alpha_1}{\alpha_0}\right)T + \left(-\frac{\alpha_2}{\alpha_0}\right)T^2 + \dots + \left(-\frac{\alpha_k}{\alpha_0}\right)T^k \\
 1 &= \left(\left(-\frac{\alpha_1}{\alpha_0}\right)T + \left(-\frac{\alpha_2}{\alpha_0}\right)T^2 + \dots + \left(-\frac{\alpha_k}{\alpha_0}\right)T^{k-1}\right)T \\
 1 \cdot T^{-1} &= \left(\left(-\frac{\alpha_1}{\alpha_0}\right) + \left(-\frac{\alpha_2}{\alpha_0}\right)T + \dots + \left(-\frac{\alpha_k}{\alpha_0}\right)T^{k-1}\right)T \cdot T^{-1} \\
 T^{-1} &= \beta_1 + \beta_2 T + \dots + \beta_k T^{k-1}
 \end{aligned}$$

where $\beta_1 = \left(-\frac{\alpha_1}{\alpha_0}\right)$, ..., $\beta_k = \left(-\frac{\alpha_k}{\alpha_0}\right)$. $\therefore T^{-1}$ is a polynomial expression in T over F .

Corollary 4.67 If V is a finite dimensional vector space over a field F and if $T \in A(V)$ is singular then there exists $S \neq 0$ in $A(V)$ such that $ST = TS = 0$.

Proof: Let $p(x) = \alpha_0 + \alpha_1 x + \alpha_2 x^2 + \dots + \alpha_k x^k$ be a minimal polynomial of T over F . (i.e.) $p(T) = 0 \Rightarrow \alpha_0 + \alpha_1 T + \alpha_2 T^2 + \dots + \alpha_k T^k = 0$. Since T is singular (i.e.) T is not invertible by Theorem 4.65, $\alpha_0 = 0$. $\therefore \alpha_1 T + \alpha_2 T^2 + \dots + \alpha_k T^k = 0 \Rightarrow (\alpha_1 + \alpha_2 T + \dots + \alpha_k T^{k-1})T = 0$ (1)

Let $S = \alpha_1 + \alpha_2 T + \dots + \alpha_k T^{k-1}$ then S is of lower degree than $p(x)$. From (1), $ST = 0$. Similarly $TS = 0$. $\therefore S \neq 0$ and $TS = 0$, where $S \neq 0$.

Corollary 4.68 If V is a finite dimensional vector space over F and if $T \in A(V)$ is right invertible then T is invertible.

Proof: Given $T \in A(V)$ is right invertible. Then there exists $U \in A(V)$ such that $TU = 1$ (1)

To prove: T is invertible. Suppose T is not invertible. (i.e.) T is singular, then by Corollary 4.67, there exists $S \neq 0$ in $A(V)$ such that $ST = TS = 0$ (2)

From (1), $TU = 0$

$$\begin{aligned}
 &\Rightarrow S(TU) = S \cdot 1 \\
 &\Rightarrow (ST)U = S \\
 &\Rightarrow 0 \cdot U = S \quad \text{by (2)} \\
 &\Rightarrow S = 0 \\
 &\Rightarrow S = 0
 \end{aligned}$$

This contradiction shows that T is invertible.

Theorem 4.69 If V is finite dimensional over F , $T \in A(V)$ is singular iff $vT = 0$ in V such that $v \neq 0$.

Proof: Assume that T is singular. By Corollary 4.67 there exists $v \neq 0 \in A(V)$ such that $ST = TS = 0$(1)

Since $v \neq 0$ in $A(V)$, there exists $w \in V$ such that $wS \neq 0$. Let $v = wS$. Then $v \neq 0$ in V , $vT = (wS)T = w(ST) = w0 = 0$ by (1) $\Rightarrow vT = 0$, $v \neq 0$. $\therefore$ There exists $v \neq 0$ in V such that $vT = 0$. Conversely, suppose that there exists $v \neq 0$ in V such that $vT = 0$. To prove: T is singular. Suppose not, T is invertible. Then there exists $U \in A(V)$ such that $UT = TU = 1$. Now, $TU = 1 \Rightarrow v(TU) = v \cdot 1$ (2)

$$v(TU) = (vT)U = 0 \cdot U = 0 \rightarrow (3)$$

From (2) and (3), $v = 0 \Rightarrow$ to $v \neq 0$. $\therefore T$ is singular.

Definition 4.70 Let $T \in A(V)$, then (range of the linear transformation T) Range of $T = \{vT/v \in V\} = VT$

Remark 4.71 (1) Range of T is a subspace of V

Proof: Let $u, v \in VT$, $\alpha, \beta \in F$. Now $(\alpha u + \beta v)T = (\alpha u)T + (\beta v)T = \alpha(uT) + \beta(vT) \in VT \Rightarrow \alpha u + \beta v \in VT$. $\therefore VT$ is a subspace of V . $\therefore$ Range of T is a subspace of V .

(2) If $VT = V$ then T is onto.

Theorem 4.72 If V is finite dimensional over F , then $T \in A(V)$ is regular iff T maps V onto V .

Proof: Suppose T is regular. To prove: T is onto. Let $v \in V$ consider vT^{-1} . Now, $(vT^{-1})T = v(T^{-1}T) = v \cdot 1 = v \Rightarrow v = (vT^{-1})T$, $v \in VT$ (i.e., every element $v \in V$ has pre-image vT^{-1} under T in V . $\therefore T$ is onto. Conversely, suppose that T is onto. To prove: T is regular. Suppose not, T is singular, we must show that T is not onto. Since T is singular, by Theorem 4.69, there exists $v_1 \neq 0$ in V such that $v_1T = 0$ ($0: V \rightarrow V$). Suppose $\alpha_1 v_1 = 0 \Rightarrow \alpha_1 = 0 \Rightarrow v_1$ is linearly independent. Since $\{v_1\}$ is linearly independent in the finite dimensional vector space. Since V is finite dimensional, we can find vectors $v_2, v_3, \dots, v_n$ such that $\{v_1, v_2, v_3, \dots, v_n\}$ form a basis of V where $\dim(V) = n$. $\therefore VT$ is generated by $w_1 = v_1T, w_2 = v_2T, \dots, w_n = v_nT$. Since $w_1 = v_1T = 0$, VT is spanned by $v_2T, v_3T, \dots, v_nT$. (i.e.) VT is spanned by $w_2, w_3, \dots, w_n \therefore \dim(VT) \leq (n-1) < n = \dim(V) \Rightarrow \dim(VT) < \dim(V) \Rightarrow VT \subset V \Rightarrow VT \neq V \Rightarrow T$ is not onto.

Note 4.73 The above theorem can be replaced as T is regular $\Leftrightarrow \dim(VT) = \dim(V)$ (i.e.) $VT = V$.

Remark 4.74 The above theorem suggest that we could use $\dim(VT)$ not only as a test for regularity but even as a measure of degree of singularity for a given $T \in A(V)$.

Consequently, $p(x)$ is the minimal polynomial of STS^{-1} also let $g(x)$ be the minimal polynomial of STS^{-1} (i.e.) $Sg(T)S^{-1} = 0 \Rightarrow Sg(T)S^{-1} = 0 \Rightarrow g(T) = 0$. (i.e.) T satisfies the polynomial of $g(x)$. Let $h(x)$ be the polynomial of degree less than the degree of $g(x)$ and $h(x) = 0$. Again $h(STS^{-1}) = Sh(T)S^{-1} = 0$. (i.e.) STS^{-1} satisfies the polynomial $h(x)$ and $\deg(h(x)) < \deg(g(x))$, which is contradiction. Consequently, $g(x)$ is a minimal polynomial of T also. Hence the theorem.

Definition 4.85 Let λ be a characteristic root of $T \in A(V)$ the element $v \neq 0$ in V is called characteristic vector of T belonging to λ if $vT = \lambda v$. (Theorem 4.81 guarantees the existence of such a characteristic vectors in V corresponding to λ)

Theorem 4.86 If $\lambda_1, \lambda_2, \dots, \lambda_k$ are distinct characteristic roots of $T \in A(V)$ and $v_1, v_2, \dots, v_k$ are characteristic vectors of T belonging to $\lambda_1, \lambda_2, \dots, \lambda_k$ respectively then $v_1, v_2, \dots, v_k$ are linearly independent over F .

Proof: **Case(i):** If $k = 1$ then there is only one characteristic vector $v_1 \neq 0$ in V which is linearly independent.

Case(ii): If $k > 1$, To prove: $v_1, v_2, \dots, v_k$ are linearly independent. Suppose the characteristic vector $v_1, v_2, \dots, v_k$ are linearly dependent over F . Then there exists scalars $\alpha_1, \alpha_2, \dots, \alpha_k$ not all zero in F such that $\alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_k v_k = 0$. Without loss of generality, let us assume that the shortest relation with non-zero coefficients (by suitably renumbering)

$$\beta_1 v_1 + \beta_2 v_2 + \dots + \beta_j v_j = 0$$

$$\text{where } \beta_1 = \beta_2 = \dots = \beta_j \neq 0$$

Since λ_i 's are characteristic roots we have

$$v_i T = \lambda_i v_i, \forall i$$

By equation(1),

$$(\beta_1 v_1 + \beta_2 v_2 + \dots + \beta_j v_j) T = 0 \cdot T \beta_1 v_1 T +$$

$$\beta_2 v_2 T + \dots + \beta_j v_j T = 0$$

$$\beta_1 (v_1 T) + \beta_2 (v_2 T) + \dots + \beta_j (v_j T) = 0$$

$$\beta_1 \lambda_1 v_1 + \beta_2 \lambda_2 v_2 + \dots + \beta_j \lambda_j v_j = 0 \quad (\beta_1 \lambda_1) v_1 +$$

$$(\beta_2 \lambda_2) v_2 + \dots + (\beta_j \lambda_j) v_j = 0 \dots \dots \dots (2)$$

$$\lambda_1 \times (1) \Rightarrow \lambda_1 \beta_1 v_1 + \lambda_2 \beta_2 v_2 + \dots + \lambda_1 \beta_j v_j = 0$$

$$(2) - (1) \Rightarrow (\lambda_2 - \lambda_1) \beta_2 v_2 + (\lambda_3 - \lambda_1) \beta_3 v_3 + \dots + (\lambda_j - \lambda_1) \beta_j v_j = 0 \dots \dots \dots (4)$$

Now, $(\lambda_j - \lambda_1) \beta_j \neq 0, i = 2, 3, \dots, j$ ($\because \lambda_j - \lambda_1 \neq 0, i > 1$ and $\beta_j \neq 0$). (i.e.)

$$\gamma_2 v_2 + \gamma_3 v_3 + \dots + \gamma_j v_j = 0 \dots \dots \dots (5)$$

$$\text{where } \gamma_2 = \lambda_2 - \lambda_1 \neq 0, \gamma_3 = \lambda_3 - \lambda_1 \neq 0, \dots, \gamma_j = (\lambda_j - \lambda_1) \neq 0 \Rightarrow$$

$v_2, v_3, \dots, v_j$ are linearly dependent. By relation (5) we have produced a shorter relation than that of equation (1) between $v_1, v_2, \dots, v_k \Rightarrow \Leftarrow$. This contradiction proves that $v_1, v_2, \dots, v_k$ are linearly independent. For example, $t \in V_3(F)$ number of characteristic root of $T \leq 3$.

Preview from Notesale.co.uk
Page 66 of 109

triangular if

$$\begin{aligned}
 v_1 T &= \alpha_{11} v_1 \\
 v_2 T &= \alpha_{21} v_1 + \alpha_{22} v_2 \\
 v_3 T &= \alpha_{31} v_1 + \alpha_{32} v_2 + \alpha_{33} v_3 \\
 &\vdots \\
 &\vdots \\
 &\vdots \\
 v_i T &= \alpha_{i1} v_1 + \alpha_{i2} v_2 + \alpha_{ii} v_i \\
 &\vdots \\
 &\vdots \\
 &\vdots \\
 v_n T &= \alpha_{n1} v_1 + \alpha_{n2} v_2 + \alpha_{nn} v_n.
 \end{aligned}$$

(i.e.) if $v_i T$ is a linear combination only if v_i and its predecessor in the basis.

Theorem 4.94 If $T \in A(V)$ has all its characteristic root in F , Then there is a basis of V in which the matrix of T is triangular.

Proof: We prove this theorem by induction on the dimension of V over F . If $\dim_F(V) = 1$. Then every matrix representation of $T \in A(V)$ is a scalar. (i.e.) A matrix of order 1×1 which is trivially a triangular matrix. Suppose the theorem is true for all vector spaces over F of dimension $(n-1)$. Let V be a vector spaces of dimension n over F . Since the linear transformation T on V has all its characteristic root in F . Let $\lambda_1 \in F$ be a characteristic root of T . Then there exists a non-zero vector $v_1 \in V$ such that $T v_1 = \lambda_1 v_1$. Let $W = \{\alpha v_1 \mid \alpha \in F\}$ then W is a subspace of V of dimension 1. Then,

$$\begin{aligned}
 WT &= \{(\alpha v_1)T \mid \alpha \in F, v_1 \in V\} \\
 &= \{\alpha(v_1 T) \mid \alpha \in F, v_1 \in V\} \\
 &= \{\alpha w_1 \mid w_1 \in V, \alpha \in F\}
 \end{aligned}$$

$\Rightarrow WT \subset W$. $\therefore W$ is a subspace of V of dimension 1 and invariant under T .

Let $\bar{V} = V/W$ then $\dim(\bar{V}) = \dim(V/W) = \dim(V) - \dim(W) = (n-1)$.

By Lemma 4.92, T induces the linear transformation $\bar{T}$ on $\bar{V}$. Also minimal polynomial of $\bar{T}$ over F divides minimal polynomial of T over F . $\therefore$ All the roots of minimal polynomial of $\bar{T}$ being the roots of minimal polynomial of T must be in F . Thus $\bar{V}$ and $\bar{T}$ satisfies the hypotheses of the theorem. Since $\dim(\bar{V}) = n-1$, then by induction hypotheses there is a basis consists of the vector $\bar{v}_2, \bar{v}_3, \dots, \bar{v}_n$ over $\bar{V}$ over F in which the matrix of $\bar{T}$ is triangular

$$\begin{aligned}
\bar{v}_2 \bar{T} &= \alpha_{22} \bar{v}_2 \\
\bar{v}_3 \bar{T} &= \alpha_{32} \bar{v}_2 + \alpha_{33} \bar{v}_3 \\
\bar{v}_4 \bar{T} &= \alpha_{42} \bar{v}_2 + \alpha_{43} \bar{v}_3 + \alpha_{44} \bar{v}_4 \\
&\vdots \\
&\vdots \\
&\vdots \\
\bar{v}_n \bar{T} &= \alpha_{n2} \bar{v}_2 + \alpha_{n3} \bar{v}_3 + \dots + \alpha_{nn} \bar{v}_n
\end{aligned}$$

Let $v_2, v_3, \dots, v_n$ be the elements of V mapping into $\bar{v}_2, \bar{v}_3, \dots, \bar{v}_n$ of $\bar{V}$ respectively. (i.e.) $\bar{v}_2 = v_2 + W$; $\bar{v}_3 = v_3 + W$; ...; $\bar{v}_n = v_n + W$. Then $v_1, v_2, \dots, v_n$ form a basis of V . Since $\bar{v}_2 \bar{T} = \alpha_{22}(v_2 + W) = \alpha_{22}v_2 + W$

$$\begin{aligned}
(v_2 + W) + \bar{T} &= \alpha_{22}v_2 + W \quad v_2 T + \\
W &= \alpha_{22}v_2 + W \\
\Rightarrow v_2 T - \alpha_{22}v_2 &\in W \\
\Rightarrow v_2 T - \alpha_{22}v_2 &\text{ is a multiples of } v_1, \text{ say } \alpha_{21}v_1 \\
\Rightarrow v_2 T - \alpha_{22}v_2 &= \alpha_{21}v_1 \\
v_2 T &= \alpha_{21}v_1 + \alpha_{22}v_2 \quad \text{Similarly} \\
v_3 T &= \alpha_{31}v_1 + \alpha_{32}v_2 + \alpha_{33}v_3
\end{aligned}$$

$$v_i T = \alpha_{i1}v_1 + \alpha_{i2}v_2 + \alpha_{ii}v_i \quad (i = 1, 2, \dots, n)$$

(i.e.) the basis $v_1, v_2, \dots, v_n$ of V over F provides us with a basis where every $v_i T$ is a linear combination of v_i and its predecessors hence the matrix of T in the basis $\{v_1, v_2, \dots, v_n\}$ is triangular.

Theorem 4.95 If V is a dimensional over F and $T \in A(V)$ has matrix $m_1(T)$ in the basis $v_1, v_2, \dots, v_n$ and $m_2(T) = C m_1(T) C^{-1}$. In fact if S is the linear transformation of V defined by $v_i S = w_i$ for $i = 1, 2, \dots, n$ then C can be chosen to be $m_1(S)$.

Remark 4.96 The above theorem can be restated as if there is a matrix $A \in F_n$ has all its characters root in F then there is matrix $C \in F_n$ such that CAC^{-1} is a triangular matrix.

Proof: Let $A \in F_n$ has all its characteristic roots in F . A defines a linear

$$2. (A + B)^* = A^* + B^*$$

$$3. (AB)^* = B^*A^* \text{ for all } A, B \in F_n$$

Definition 4.117 Suppose F be a field of complex numbers and that adjoint $*$ on F_n is the hermitian adjoint. The matrix A is called hermitian if $A^* = A$.

Definition 4.118 A is called skew hermitian if $A^* = -A$

Remark 4.119

1. Any square matrix A can be uniquely written as a sum of a hermitian and a skew hermitian matrices

$$A = \frac{1}{2}(A + A^*) + \frac{1}{2}(A - A^*)$$

2. If $A \neq 0 \in F_n$ then trace of $AA^* > 0$

3. If $A_1, A_2, \dots, A_k \in F_n$ and if $A_1A_1^* + A_2A_2^* + \dots + A_kA_k^* = 0$ then
 $A_1 = A_2 = \dots = A_k = 0$

4. If λ is a scalar matrix then $\lambda^* = \bar{\lambda}$

Example 4.120

$$\lambda = \begin{pmatrix} -3i & 0 \\ 0 & 3i \end{pmatrix}; \lambda^* = \begin{pmatrix} -3i & 0 \\ 0 & -3i \end{pmatrix}; \bar{\lambda} = \begin{pmatrix} -3i & 0 \\ 0 & -3i \end{pmatrix} \Rightarrow \lambda^* = \bar{\lambda}$$

Result 4.121 The characteristics roots of a hermitian matrix are all real (i.e.) if a complex number λ is a characteristic roots of a hermitian matrix then λ must be real.

Proof: Let A be a hermitian matrix then $A = A^*$ (i.e.) $\bar{A}^T = A$ and λ be a characteristic root of $T \in A(V)$. Let X be a characteristics vector

$$\begin{aligned}
\therefore k_1 = k_2 = \dots = k_m = 0 \\
k_1 = 0 \Rightarrow f_{11}w_1 + f_{12}w_2 + \dots + f_{1n}w_n = 0 \\
k_2 = 0 \Rightarrow f_{21}w_1 + f_{22}w_2 + \dots + f_{2n}w_n = 0 \\
\vdots \\
\vdots \\
\vdots \\
k_m = 0 \Rightarrow f_{m1}w_1 + f_{m2}w_2 + \dots + f_{mn}w_n = 0 \dots\dots\dots (5)
\end{aligned}$$

Since $\{w_1, w_2, \dots, w_n\}$ forms the basis of K over F they are linearly independent over F .

from (5) we have,

$$\begin{aligned}
f_{11} = f_{12} = \dots = f_{1n} = 0 \\
f_{21} = f_{22} = \dots = f_{2n} = 0 \\
\vdots \\
\vdots \\
\vdots \\
f_{m1} = f_{m2} = \dots = f_{mn} = 0
\end{aligned}$$

(i.e.) $f_{ij} \forall i = 1, 2, \dots, m, j = 1, 2, \dots, n. \therefore S = \{v_i w_j \mid i = 1, 2, \dots, m, j = 1, 2, \dots, n\}$ is linearly independent. (6)

From (2) and (3), the set S which contains mn elements forms the basis of

L over $F. \therefore [L : F] = \dim_F(L) = mn = [m][K : F].$ (7)

Since $[L : K]$ and $[K : F]$ are finite $\Rightarrow [L : F]$ is finite by (7). $\therefore L$ is a finite extension of F .

Corollary 5.10 If L is a finite extension of F and K is a subfield of L which contains F , then $[K : F] \mid [L : F]$.

Proof: Given L, K, F are fields, such that $L \supset K \supset F$ and $[L : F]$ is finite. Clearly any element in L , linearly independent over K , linearly independent over F . From the assumption $[L : F]$ is finite we come to conclusion that $[K : F]$ is finite. By previous theorem, $[L : F] = [L : K][K : F]$. Hence $[K : F] \mid [L : F]$.

Definition 5.11 An element $a \in K$ is said to be algebraic over F if there exists elements $\alpha_0, \alpha_1, \alpha_2, \dots, \alpha_n \in F$, not all zero such that $\alpha_0 a^n + \alpha_1 a^{n-1} + \dots + \alpha_n = 0$.

Remark 5.12 if $p(x) = \alpha_0 x^n + \alpha_1 x^{n-1} + \dots + \alpha_n, \alpha_i \in F. \therefore \alpha_0 a^n + \alpha_1 a^{n-1} + \dots + \alpha_n = 0 \Rightarrow p(a) = 0$. (i.e.) $a \in K$ is algebraic over F if there is a non-zero polynomial $p(x) \in F[x]$ which satisfies a . (i.e.) $p(a) = 0$.

For example, $p(x) = x^3 + 3x^2 + 3x + 1 \Rightarrow p(-1) = 0 \Rightarrow -1$ is algebraic over $\mathbb{Q}$ and 1 is not algebraic over $\mathbb{Q}$.

Let $\alpha, \beta \in F$ such that $\alpha\psi = \beta\psi$,

$$\begin{aligned} V + \alpha &= V + \beta \\ (\alpha - \beta) &\in V = p(x) \\ (\alpha - \beta) &= f(x)p(x) \text{ for some } f(x) \in F[x] \\ \Rightarrow f(x) &= 0 \\ \Rightarrow (\alpha - \beta) &= 0 \\ \Rightarrow \alpha &= \beta \psi \\ &\text{is } 1 - 1. \end{aligned}$$

(ii) ψ is homomorphism:

$$\begin{aligned} (\alpha + \beta)\psi &= V + (\alpha + \beta) \\ &= (V + \alpha) + (V + \beta) \\ &= \alpha\psi + \beta\psi \end{aligned}$$

$\therefore \psi$ is a homomorphism.

Thus ψ is an isomorphism from F into E . Let $\bar{F}$ be the image of F into E under ψ . Let $\bar{F} = \{\alpha + V \mid \alpha \in F\}$. Thus ψ is an isomorphism of F onto $\bar{F}$ and $\bar{F}$ is a subfield of E isomorphic to F by the mapping $\psi : F[x] \rightarrow E$, by $f(x)\psi = f(x) + V$ and the restriction of ψ to F induces an isomorphism of F onto $\bar{F}$. If we identify F and $\bar{F}$ under this isomorphism we can consider E to be an extension of F .

Claim: E is a finite extension of F of degree n equal to degree of $p(x)$. First we shall prove that the n elements $\{1+V, x+V, (x+V)^2 = x^2+V, (x+V)^3 = x^3+V, \dots, (x+V)^{n-1} = x^{n-1}+V\}$ form a basis of E over F . $[E:F] = n$. Finally we shall show that $p(x)$ has a root in E . Let $p(x) = \beta_0 + \beta_1 x + \beta_2 x^2 + \dots + \beta_k x^k$ where $\beta_0, \beta_1, \beta_2, \dots, \beta_k \in F$. First Let us make $p(x)$ be a polynomial over E with help of the identification we have made between F and $\bar{F}$. For convenience of notation Let us denote the element $x\psi = x + V$ in the field E as x_k by $\beta_k + V$, $p(x) = (\beta_0 + V) + (\beta_1 + V)x + \dots + (\beta_k + V)x^k$. We shall show that $x + V \in E$ satisfies $p(x)$.

$$\begin{aligned} p(x+V) &= (\beta_0 + V) + (\beta_1 + V)(x+V) + \dots + (\beta_k + V)(x+V)^k \\ &= (\beta_0 + V) + (\beta_1 + V)(x+V) + (\beta_2 + V)(x^2 + V) + \dots \\ &\quad + (\beta_k + V)(x^k + V) \\ &= (\beta_0 + \beta_1 x + \beta_2 x^2 + \dots + \beta_k x^k) + V \\ &= p(x) + V \\ &= 0 \quad (\because p(x) \in V) \\ &= \text{zero element of } E. \end{aligned}$$

Thus $(x+V)$ satisfies $p(x)$. $\therefore$ An element $x+V$ in the extension E satisfies the polynomial $p(x) \in F[x]$. The field E has been shown to satisfy all the

$$\begin{aligned}
(f(x))\tau^* &= g(x)\tau^* \\
\Rightarrow (\alpha_0x^n + \alpha_1x^{n-1} + \dots + \alpha_n)\tau^* &= (\beta_0x^m + \beta_1x^{m-1} + \dots + \beta_m)\tau^* \\
\Rightarrow \alpha'_0t^n + \alpha'_1x^{n-1} + \dots + \alpha'_n &= \beta'_0t^m + \beta'_1x^{m-1} + \dots + \beta'_m \\
\Rightarrow n = m \text{ and } \alpha'_i &= \beta'_i, i = 0, 1, \dots, n \\
\Rightarrow n = m \text{ and } (\alpha_i)\tau &= (\beta_i)\tau, i = 0, 1, 2, \dots, n \\
\Rightarrow n = m \text{ and } \alpha_i &= \beta_i, i = 0, 1, 2, \dots, n \quad (\because \tau \text{ is 1-1}) \\
f(x) &= g(x)
\end{aligned}$$

τ^* is onto: Let $\gamma'_0t^n + \gamma'_1x^{n-1} + \dots + \gamma'_n$ be any element of $F'[t]$, $\gamma'_i \in F'$ since τ is onto, there exists $\gamma_0, \gamma_1, \dots, \gamma_n \in F$ such that $(\gamma_0)\tau = \gamma'_0, (\gamma_1)\tau = \gamma'_1, \dots, (\gamma_n)\tau = \gamma'_n$. Now $\gamma_0x^n, \gamma_1x^{n-1}, \dots, \gamma_n \in F[x]$ and $(\gamma_0x^n, \gamma_1x^{n-1}, \dots, \gamma_n)\tau^* = (\gamma'_0t^n + \gamma'_1x^{n-1} + \dots + \gamma'_n)$. $\therefore \tau^*$ is onto.

τ^* is a homomorphism: To Prove: $(f(x) + g(x))\tau^* = f(x)\tau^* + g(x)\tau^*$

$$\begin{aligned}
[f(x) + g(x)]\tau^* &= [\alpha_0x^n + \alpha_1x^{n-1} + \dots + \alpha_n + \beta_0x^m + \beta_1x^{m-1} + \dots + \beta_m]\tau^* \\
&= ((\alpha'_0x^n + \alpha'_1x^{n-1} + \dots + \alpha'_n) + (\beta'_0x^m + \beta'_1x^{m-1} + \dots + \beta'_m))\tau^* \\
&= (\alpha_0x^n + \alpha_1x^{n-1} + \dots + \alpha_n)\tau^* + (\beta_0x^m + \beta_1x^{m-1} + \dots + \beta_m)\tau^* \\
&= f(x)\tau^* + g(x)\tau^*
\end{aligned}$$

Hence τ^* is an isomorphism of $F[x]$ onto $F'[t]$.

Remark 5.44

- Further if $f(x) \in F[x]$ be simply taken as α where $\alpha \in F$ then $(f(x))\tau^* = \alpha\tau^* = \alpha\tau = \alpha'$

From the above theorem we conclude that factorisation of $f(x)$ in $F[x]$ result in like factorisation of $f(x)\tau^* = f'(t)$ in $F'[t]$ and vice versa. In particular $f(x)$ is irreducible in $F[x]$ iff $f'(t)$ is irreducible in $F'[t]$.

Lemma 5.45 Let τ be an isomorphism of a field F onto a field F' defined by $(\alpha)\tau = \alpha' \forall \alpha \in F$ for an arbitrary polynomial $f(x) = (\alpha_0x^n + \alpha_1x^{n-1} + \dots + \alpha_n) \in F[x]$. Let us define $f'(t) = \alpha'_0t^n + \alpha'_1x^{n-1} + \dots + \alpha'_n \in F'[t]$. If $f(x)$ is irreducible in $F[x]$, show that there is an isomorphism τ^{**} of $F[x]/f(x)$ onto $F'[t]/f'(t)$ with the property that $\alpha\tau^{**} = \alpha'(x + f(x))\tau^{**} = t + f'(t)$.

Proof: Let $\tau^*: F[x] \rightarrow F'[t]$ defined by $f(x)\tau^* = f'(t)$. Then by Lemma 5.43 τ^* is an isomorphism of $F[x]$ onto $F'[t]$. Let $f(x)$ be irreducible in $F[x]$ then $f'(t)$ will be irreducible in $F'[t]$. $V = (f(x))$ ideal generated by $f(x)$ in $F[x]$ and $V' = (f'(t))$ ideal in $F'[t]$. Now, $f(x)$ and $f'(t)$ are irreducible both V and V' are maximal ideal. $F[x]/V$ and $F'[t]/V'$ are fields. Define $\tau^{**}: F[x]/V \rightarrow F'[t]/V'$ by $(g(x) + V)\tau^{**} = g(x)\tau^* + V' = g'(t) + V'$.

τ^{**} is well defined: For this we have to show that if $V + g(x) = V + h(x)$