Similar Formulas 5.1.1

$$\cos(\theta) = \frac{e^{i\theta} + e^{-i\theta}}{2}$$
(5.7)

$$\sin(\theta) = \frac{e^{i\theta} - e^{-i\theta}}{2i} \tag{5.8}$$

$$\cos(z) = \frac{e^{iz} + e^{-iz}}{2}$$
(5.9)

$$\sin(z) = \frac{e^{iz} - e^{-iz}}{2}$$
(5.10)

$$\cosh z = \frac{e^z + e^{-z}}{2} \tag{5.11}$$

$$\sinh \, z = \frac{e^z - e^{-z}}{2} \tag{5.12}$$

$$\cosh iz = \cos z \tag{5.13}$$

$$\sinh iz = i\sin z \tag{5.14}$$

De Moivre's Theorem 5.1.2

$$(\cos\theta + i\sin\theta)^n = \cos n\theta + i\sin n\theta \tag{5.15}$$

From this it can be shown with $z = e^{i\theta}$

$$z^{n} + \frac{1}{z^{n}} = 2 \cos n\theta \qquad z^{n} - \frac{1}{z^{n}} = 2i \sin n\theta \qquad (5.16)$$
5.1.3 Roots of unity
$$n^{n} \in \mathbf{1} = e^{2k.} \Rightarrow z = e^{i2k\pi/n} \mathbf{15} \qquad (5.17)$$
where k is an integer and will take values 0, 12, **6**n - **0** to give the n distinct roots
5**5.4** Eogarithms
with $z = re^{i(\theta + 2n\pi)}$

$$Ln \ z = ln \ r + i(\theta + 2n\pi) \qquad (5.18)$$

$$Ln \ z = ln \ r + i(\theta + 2n\pi) \tag{5.18}$$

Restricting to principal value by constraining the argument of z to lie between $-\pi t \sigma \pi$ we get singlevalued Ln(z)

The definition of complex number raised to a complex power is in terms of already defined complex functions:

$$t^z = e^{z \ln(t)} \tag{5.19}$$

Complex Functions 5.2

$$\lim_{z \to z_0} f(z) = \infty \text{ if and only if } \lim_{z \to z_0} \frac{1}{f(z)} = 0$$
(5.20)

$$\lim_{z \to \infty} f(z) = w_0 \text{ if and only if } \lim_{z \to 0} f \frac{1}{z} = w_0$$
(5.21)

$$\lim_{z \to \infty} f(z) = \infty \text{ if and only if } \lim_{z \to 0} \frac{1}{f(1/z)} = 0$$
(5.22)

Since x and y are related to z and its complex conjugate z^* by

$$x = \frac{1}{2}(z + z^*)$$
 and $y = \frac{1}{2i}(z - z^*)$, (24.6)

we may formally regard any function f = u + iv as a function of z and z^* , rather than x and y. If we do this and examine $\partial f / \partial z^*$ we obtain

$$\frac{\partial f}{\partial z^*} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial z^*} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial z^*}
= \left(\frac{\partial u}{\partial x} + i\frac{\partial v}{\partial x}\right) \left(\frac{1}{2}\right) + \left(\frac{\partial u}{\partial y} + i\frac{\partial v}{\partial y}\right) \left(-\frac{1}{2i}\right)
= \frac{1}{2} \left(\frac{\partial u}{\partial x} - \frac{\partial v}{\partial y}\right) + \frac{i}{2} \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y}\right).$$
(24.7)

Now, if f is analytic then the Cauchy–Riemann relations (24.5) must be satisfied, and these immediately give that $\partial f/\partial z^*$ is identically zero. Thus we conclude that if f is analytic then f cannot be a function of z^* and any expression representing an analytic function of z can contain x and y only in the combination x + iy, not in the combination x - iy.

5.2.1 Cauchy-Reimann Equations

Suppose that for a complex-valued function

$$f(z) = u(x, y) + iv(x, y)$$
(5.23)

(5.25)

(5.26)

f'(z) exists at a point $z_0 = (x_0, y_0)$. Then the first-order partial derivatives of u and v must exist at (x_0, y_0) and they must satisfy the Cauchy-Reimann Equations:

$$u_x = v_y$$
, $u_y = -v_x$
 $f'(z_0) = u_x + iv_x$

And also

- Differntiation of cauchy equations provides us with the x at both u and v individually satisfy laplace equations in 2D
- The family of 21 curves (in xy plan (y, y) = constant and v(x, y) = constant intersect at right argues to each other.
- For multivalued complex function f(z), like exp(z), Lnz, $z^{1/2}$ etc. we can make them single valued and then use the analytic function analysis on it by concept of branch points and cuts
- Branch point is a point in Argand plane such that if z is varied in a closed loop enclosing the branch point, f(z) doesn't return to its original value, although z does since $\theta \to \theta + 2\pi$ doesn't affect z.
- Branch cuts are lines in the argand diagram, finite or infinite that prevents us to ever make a closed loop enclosing a branch point.
- So, if we dont cross the branch cut, f(z) remains single-valued.

5.2.2 Singularities

- Isolated singularity: when f(z) isnt analytic at z_0 but analytic at all points in the neighbourhood.
- Pole: most imp isolated singularity
- If

$$f(z) = \frac{g(z)}{(z - z_0)^n}$$
(5.27)

such that $g(z_0) \neq 0$ and is analytic in neighbourhood of z_0 then its a pole of order n

$$\nabla \times \mathbf{A} = \frac{1}{r} \begin{vmatrix} \hat{\mathbf{r}} & r\hat{\theta} & \hat{\mathbf{z}} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial z} \\ A_1 & rA_2 & A_3 \end{vmatrix}$$
(6.11)

Spherical

$$\nabla f = \frac{\partial f}{\partial r} \hat{\mathbf{r}} + \frac{1}{r \sin \phi} \frac{\partial f}{\partial \theta} \hat{\boldsymbol{\theta}} + \frac{1}{r} \frac{\partial f}{\partial z} \hat{\boldsymbol{\phi}}$$
(6.12)

$$\nabla \mathbf{A} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 A_1) + \frac{1}{r \sin \phi} \frac{\partial A_2}{\partial \theta} + \frac{1}{r \sin \phi} \frac{\partial}{\partial \phi} (\sin \phi A_3)$$
(6.13)

$$\nabla \times \mathbf{A} = \frac{1}{r^2 \sin\phi} \begin{vmatrix} \hat{\mathbf{r}} & r\sin\phi \hat{\boldsymbol{\theta}} & r\hat{\boldsymbol{\phi}} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ A_1 & r\sin\phi A_2 & rA_3 \end{vmatrix}$$
(6.14)

$$\nabla^2 = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \left(\frac{\partial^2}{\partial \phi^2} \right)$$
(6.15)

6.2.5 Fundamental theorems

The line integral of any gradient field doesn't depend on path but just on the endpoints. The little changes df add up (the integral on LHS) to give f(b) - f(a)

$$\int_{a}^{b} (\nabla f) \cdot d\mathbf{l} = f(b) - f(a)$$
(6.16)

The volume integral of a divergence over any given volumen is equal to the close text for integral or the flux of the original vector field over the surface that bounds that volume

The surface integral of carbor a vector field is equal to the closed line integral of that field over the boundary of the surface. Since for the closed located by there can be infinite number of surfaces, it shows that surface integral of curls is only dependent on the boundary of the surface.

$$\int_{S} (\nabla \times \mathbf{A}) . d\mathbf{a} = \int \mathbf{A} . d\mathbf{l}$$
(6.18)

These operators are usually applied on scalar (gradient) and vector (divergence, curl) fields. Boldface notation is used for vector fields. f and g are scalar fields and k is just a scalar number

6.2.6 First derivatives

• Sum rules

$$\nabla(f+g) = \nabla f + \nabla g \tag{6.19}$$

$$\nabla .(\mathbf{A} + \mathbf{B}) = (\nabla . \mathbf{A}) + (\nabla . \mathbf{B})$$
(6.20)

$$\nabla \times (\mathbf{A} + \mathbf{B}) = (\nabla \times \mathbf{A}) + (\nabla \times \mathbf{B})$$
(6.21)

• Multiplying by a constant rules

$$\nabla(kf) = k\nabla f \tag{6.22}$$

$$\nabla .(k\mathbf{A}) = k(\nabla .\mathbf{A}) \tag{6.23}$$

$$\nabla \times (k\mathbf{A}) = k(\nabla \times \mathbf{A}) \tag{6.24}$$

Chapter 7

Coordinate Systems

7.1 Cartesian coordinates

Straightforward and easy to understand formulas for all things.

• Point P(x,y,z)

where x, y and z denotes the distances along the x,y and z axes respectively.

The position vector of any point P is given by $OP = x\hat{x} + y\hat{y} + z\hat{z}$ where the unit vectors are \hat{x} , \hat{y} and \hat{z} that are fixed in magnitude(=1) and direction also. So in any problem with changing position/displacement vector, their time derivative must be zero

where d = perpendicular distance of plane from origin

• In intercept form:

$$\frac{x}{a} + \frac{y}{b} + \frac{z}{c} = 1 \tag{7.4}$$

• Relation b/w unit normal and intercepts:

$$\hat{n} \propto \frac{\hat{i}}{a} + \frac{\hat{j}}{b} + \frac{\hat{k}}{c} \tag{7.5}$$

• Angle between two planes: $l_1x + m_1y + n_1z = d_1$ and $l_2x + m_2y + n_2z = d_2$ is:

$$\cos\theta = \frac{l_1 l_2 + m_1 m_2 + n_1 n_2}{\sqrt{l_1^2 + m_1^2 + n_1^2} \sqrt{l_2^2 + m_2^2 + n_2^2}}$$
(7.6)

• Laplacian

$$\nabla .(\nabla f) = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2}$$
(7.7)

• Laplacian of a vector

$$\nabla^2 \mathbf{v} \equiv (\nabla^2 v_x) \hat{x} + (\nabla^2 v_y) \hat{y} + (\nabla^2 v_z) \hat{z}$$
(7.8)

3D spherical polar

Line element:

$$ds^{2} = dr^{2} + r^{2}d\theta^{2} + r^{2}\sin^{2}\theta d\phi^{2}$$
(7.21)

Volume element:

Cylindrical

Line element:

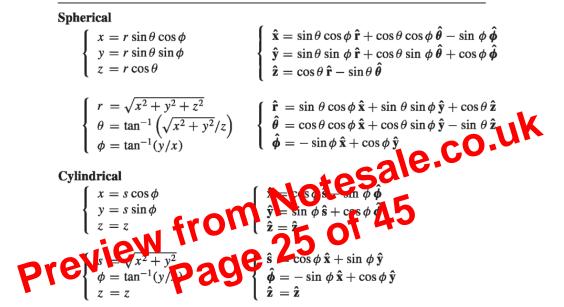
Volume element:

 $ds^2 = d\rho^2 + \rho^2 d\phi^2 + dz^2 \tag{7.23}$

$$dV = \rho d\phi d\rho dz \tag{7.24}$$

(7.22)

7.4 Coordinate transformations and unit vectors



SPHERICAL AND CYLINDRICAL COORDINATES

 $dV = r^2 \sin \theta d\phi d\theta dr$

12.2 Fourier integral and transforms

Fourier cosine integral which applies to an even function f(x)

$$A(w) = \frac{2}{\pi} \int_0^\infty f(x) \cos wx \, dx \quad f(x) = \int_0^\infty A(w) \cos wx \, dw$$
(12.6)

Fourier sine integral which applies to an odd function f(x)

$$B(w) = \frac{2}{\pi} \int_0^\infty f(x) \sin wx \, dx \quad f(x) = \int_0^\infty B(w) \sin wx \, dw$$
(12.7)

For a general function f(x), we have representation in terms of its fourier integral. Here the series of eq. 11.1 transforms to an integral as we take $L \to \infty$

$$f(x) = \int_0^\infty [A(w)\cos wx + B(w)\sin wx]dw$$
(12.8)

$$A(w) = \frac{1}{\pi} \int_{-\infty}^{\infty} f(v) \cos wv \, dv, \quad B(w) = \frac{1}{\pi} \int_{-\infty}^{\infty} f(v) \sin wv \, dv \tag{12.9}$$

Writing in complex and doing few tricks we get:

$$\hat{f}(k) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} f(x)e^{-ikx}dx \qquad (12.10)$$

$$f(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \hat{f}(k) e^{ikx} dk$$
(12.11)
cosine transforms
$$\sqrt{2} \int_{-\infty}^{\infty} e^{-ikx} dk = 0$$

12.2.1 Fourier sine and cosine transforms

$$\hat{f}_s(k) = \sqrt{\frac{2}{\pi}} \int_{-\infty}^{\infty} f(x) \sin x \, dx$$
(12.12)

$$f(\mathbf{O}) = \sqrt{\frac{2}{\pi}} \int_{0}^{\infty} \hat{f}(\mathbf{b}) \sin \theta d\mathbf{k} \mathbf{A}^{\mathbf{O}}$$
(12.13)

$$\hat{\mathbf{p}}_{\pi}^{2} \mathbf{A} \mathbf{A} = \int_{0}^{\infty} f(x) \cos kx \, dx \qquad (12.14)$$

$$f(x) = \sqrt{\frac{2}{\pi}} \int_0^\infty \hat{f}_c(k) \cos kx \ dk$$
(12.15)

Properties

$$\mathcal{F}_{s}\{f'(x)\} = -k\mathcal{F}_{c}\{f(x)\}$$
(12.16)

$$\mathcal{F}_{c}\{f'(x)\} = k\mathcal{F}_{s}\{f(x)\} - \sqrt{\frac{2}{\pi}}f(0)$$
(12.17)

$$\mathcal{F}_{c}\{f''(x)\} = -k^{2}\mathcal{F}_{c}\{f(x)\} - \sqrt{\frac{2}{\pi}}f'(0)$$
(12.18)

$$\mathcal{F}_{s}\{f''(x)\} = -k^{2}\mathcal{F}_{s}\{f(x)\} + \sqrt{\frac{2}{\pi}}kf(0)$$
(12.19)

$$\frac{d}{dk}\mathcal{F}_s(k) = \mathcal{F}_c\{xf(x)\}\tag{12.20}$$

$$\frac{d}{dk}\mathcal{F}_c(k) = -\mathcal{F}_s\{xf(x)\}\tag{12.21}$$

13.1.3 Poisson distribution

This distribution is actually a discrete distribution cause the random variable is discrete. But that random variable is spread over a continuum. Like the number of calls that we will receive over some particular time interval.

$$P_x(t) = \frac{(\lambda t)^x}{x!} e^{-\lambda t}$$
(13.22)

This is the probability of receiving x number of calls in a time period of t given that λ is the average number of calls per unit time.

Mean and variance are both λ

13.1.4 Gaussian distribution

Many random variables occuring in physical sciences and others follow this distribution exactly or approximately.

The probability density function is:

$$f(x) = \frac{1}{\sigma\sqrt{2\pi}} exp\left[-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2\right]$$
(13.23)

Mean and variance can be changed by shift of origin and scaling. Then with standard variable $Z = (X - \mu)/\sigma$

$$\phi(z) = \frac{1}{\sqrt{2\pi}} exp\left(-z^2/2\right) \tag{13.24}$$

The cumulative probability function can be solved analytically but is tabulated as $\Phi(z)$ for different z values.

$$F(x) = \Phi\left(\frac{x-\mu}{\sigma}\right)$$
(13.25)
$$X \le b) = \Phi\left(\frac{b-c}{\sigma}\right) \Phi\left(\frac{5-\mu}{\mu}\right)$$
(13.26)

- 13.2 Random walk Warners k
 - Sim list and om walk: Walk this e on steps by flipping a coin. If head comes move forward, tail comes move backwards.

2 01

- Parameters: N = total number of steps taken. l = length of each step. n = the integer (if l = 1) where you landed at the end.
- Pattern on analysis probabilities of different possible ns when N changes.

п	-5	-4	-3	-2	-1	0	1	2	3	4	5
<i>f</i> ₀ (<i>n</i>)						1					
2f ₁ (n)					1		1				
2 ² f ₂ (n)				1		2		1			
2 ³ f ₃ (n)			1		3		3		1		
2 ⁴ f ₄ (n)		1		4		6		4		1	
2 ⁵ f ₅ (n)	1		5		10		10		5		1

- Thus, the coefficients are binomial
- If number of heads = $n_{forward}$ and tails = $n_{backward}$ get fixed then final position is fixed $n = n_{forward} n_{backward}$.