Example: If
$$A = \begin{bmatrix} 1 & 0 & 2 & 5 \\ 2 & -1 & 3 & 7 \end{bmatrix}$$
, then $A' = \begin{bmatrix} 1 & 2 \\ 0 & -1 \\ 2 & 3 \\ 5 & 7 \end{bmatrix}$

Properties of Transpose of a Matrix

- If A' and B' denote the transposes of A and B respectively, then
- (a) (A')' = A i.e., the transpose of the transpose of a matrix is the matrix itself.
- (b) (A+B)' = A' + B' i.e., the transpose of the sum of two matrices is equal to the sum of their transposes.
- (c) (AB)' = B'A' i.e., the transpose of the product of two matrices is equal to the product of their transposes taken in the reverse order.
 1.5: Symmetric Matrix
 A some matrix A = {a, } is saidted be symmetric if A' = A i.e., if the transpose of the matrix is equal to the product of the restrict if A' = A i.e., if the transpose of the matrix is equal to the restrict if A' = A i.e., if the transpose of the matrix is equal to the restrict if A' = A i.e., if the transpose of the matrix is equal to the restrict if A' = A i.e., if the transpose of the matrix is equal to the restrict if A' = A i.e., if the transpose of the matrix is equal to the restrict if A' = A i.e., if the transpose of the matrix is equal to the restrict if A' = A i.e., if the transpose of the matrix is equal to the restrict if A' = A i.e., if the transpose of the matrix is equal to the restrict if A' = A i.e., if the transpose of the matrix is equal to the restrict if A' = A i.e., if the transpose of the matrix is equal to the restrict is in the transpose of the matrix is equal to the restrict if A' = A i.e., if the transpose of the matrix is equal to the restrict if A' = A i.e., if the transpose of the matrix is equal to the restrict if A' = A i.e., if the transpose of the matrix is equal to the restrict if A' = A i.e., if the transpose of the matrix is equal to the restrict if A' = A i.e., if the transpose of the matrix is equal to the restrict if A' = A i.e., if the transpose of the matrix is equal to the restrict if A' = A i.e., if the transpose of the matrix is equal to the restrict is a interval to the restrict if A' = A i.e., if the transpose of the matrix is equal to the restrict if A' = A i.e., if the transpose of the transpose of the restrict is a interval to the transpose of the transpose of

tric if A' = A i.e., if the **transpose of the matrix** is equal to the matrix it el

Thus, for a symmetric matrix
$$A = \{a_{ij}\}, a_{ij} = a_{ji}$$
.

Example : $\begin{bmatrix} -1 & 2 & 3 \\ 2 & 5 & 6 \\ 3 & 6 & 4 \end{bmatrix}, \begin{bmatrix} a & h & g \\ h & b & f \\ g & f & c \end{bmatrix}$ are symmetric matrices.

1.6: Skew-Symmetric Matrix

A square matrix $A = \{a_{ij}\}$ is said to be symmetric if A' = -A i.e., if the transpose of the matrix is equal to the negative of the matrix.

Thus, for a symmetric matrix $A = \{a_{ii}\}, a_{ii} = -a_{ii}$.

Putting j=i, $a_{ii} = -a_{ii} \Longrightarrow 2a_{ii} = 0$ or $a_{ii} = 0$ for all *i*. Thus, all diagonal elements of a skewsymmetric matrix are zero.

Example :
$$\begin{bmatrix} 0 & 2 & -3 \\ -2 & 0 & 1 \\ 3 & -1 & 0 \end{bmatrix}$$
, $\begin{bmatrix} 0 & h & -g \\ -h & 0 & f \\ g & -f & 0 \end{bmatrix}$ are skew-symmetric matrices.

is the conjugate transpose of A.

Solution:
$$A' = \begin{bmatrix} 2+i & -5\\ 3 & i\\ -1+3i & 4-2i \end{bmatrix}$$

 $A^{\theta} = \overline{(A')} = \begin{bmatrix} 2-i & -5\\ 3 & -i\\ -1-3i & 4+2i \end{bmatrix}$
 $A^{\theta}A = \begin{bmatrix} 2-i & -5\\ 3 & -i\\ -1-3i & 4+2i \end{bmatrix} \begin{bmatrix} 2+i & 3 & -1+3i\\ -5 & i & 4-2i \end{bmatrix}$
 $= \begin{bmatrix} 30 & 6-8i & -19+17i\\ 6+8i & 10 & -5+5i\\ -19-17i & -5-5i & 30 \end{bmatrix} = B(say)$
Now $B' = \begin{bmatrix} 30 & 6+8i & -19+17i\\ 6-8i & 10 & -5+5i\\ -19-17i & -5-5i & 30 \end{bmatrix} = B(say)$
Now $B' = \begin{bmatrix} 30 & 6+8i & -19+17i\\ 6-8i & 10 & -5+5i\\ -19-17i & -5-5i & 30 \end{bmatrix} = B$

Hence $B = A^{\theta}A$ is a Hermitian matrix.

Example 2: If A and B are Hermitian, show that AB-BA is skew-Hermitian.

Solution: A and B are Hermitian $\Rightarrow A^{\theta} = A$ and $B^{\theta} = B$ Now $(AB - BA)^{\theta} = (AB)^{\theta} - (BA)^{\theta}$ $B^{\theta}A^{\theta} - A^{\theta}B^{\theta} = BA - AB = -(AB - BA)$ $\Rightarrow AB - BA$ is skew-Hermitian.

Example3: If A is a skew-Hermitian matrix, then show that iA is Hermitian.

Solution: A is a skew- Hermitian matrix $\Rightarrow A^{\theta} = -A$ Now $(iA)^{\theta} = \bar{i}A^{\theta} = (-i)(-A) = iA$

$$\mathbf{A} = \begin{bmatrix} 2 & 2-2i & 1-4i \\ 2+2i & 3 & i \\ 1+4i & -i & 9 \end{bmatrix} + \begin{bmatrix} 2i & 2+2i & 4-i \\ -2+2i & i & 4+i \\ -4-i & -4+i & 0 \end{bmatrix}$$

Example 6: Show that the matrix
$$A = \frac{1}{\sqrt{3}} \begin{bmatrix} 1 & 1+i \\ 1-i & -1 \end{bmatrix}$$
 is unitary.
Solution: Given $A = \frac{1}{\sqrt{3}} \begin{bmatrix} 1 & 1+i \\ 1-i & -1 \end{bmatrix}$
 $\therefore A^{\theta} = (\overline{A}') = \frac{1}{\sqrt{3}} \begin{bmatrix} 1 & 1+i \\ 1-i & -1 \end{bmatrix}$
Now $AA^{\theta} = \frac{1}{3} \begin{bmatrix} 1 & 1+i \\ 1-i & -1 \end{bmatrix} \begin{bmatrix} 1 & 1+i \\ 1-i & -1 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 3 & 0 \\ 0 & 3 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I$.
Similarly $A^{\theta}A = I$.
 $\therefore AA^{\theta} = I = A^{\theta}A$.
Hence A is unitary.
Example 7: If $N = \begin{bmatrix} 0 & 1+2i \\ 1+i & 0 \end{bmatrix}$
Key bottom: Given $P = A = I$.
 $N = \begin{bmatrix} 0 & 1+2i \\ -1+2i \end{bmatrix}$ for $H = I = A^{\theta}A$.
 $N = \begin{bmatrix} 0 & 1+2i \\ -1+2i \end{bmatrix}$ for $H = I = A^{\theta}A$.
 $N = \begin{bmatrix} 0 & 1+2i \\ -1+2i \end{bmatrix}$ for $H = I = A^{\theta}A$.
 $N = \begin{bmatrix} 0 & 1+2i \\ -1+2i \end{bmatrix}$ for $H = I = A^{\theta}A$.
 $A = I$

Properties of Inverse of a Matrix

- (1) Inverse of A exists only if $|A| \neq 0$ i.e. A is non-singular matrix.
- (2) Inverse of a matrix is unique.
- (3) Inverse of a `product is the product of inverses in the reverse order

i.e., (AB)⁻¹=B⁻¹A⁻¹

(4) Transposition and inverse are commutative i.e., $(A^{-1})^T = (A^T)^{-1}$, $(A^{-1})^{-1} = A$.

Example1: Find the inverse of A by Gauss-Jordan method where

	1	2	3]
A =	2	4	5
	3	5	6

$A = \begin{bmatrix} 1 & 2 & 5 \\ 2 & 4 & 5 \\ 3 & 5 & 6 \end{bmatrix}$	
Solution : Writing A=IA i.e.,	•
$\begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 5 \\ 3 & 5 & 6 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} A$	
Solution : Writing A=IA i.e., $ \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 5 \\ 3 & 5 & 6 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} $ A notesale could be added and a second sec	
By R ₂₃ $\begin{bmatrix} 1 & 2 & 3 \\ 0 & -1 & -3 \\ 0 & 0 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ -3 & 0 & 1 \\ -2 & 1 & 0 \end{bmatrix} A$	
By R ₁₃ (3),R ₂₃ (-3) $\begin{bmatrix} 1 & 2 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix} = \begin{bmatrix} -5 & 3 & 0 \\ 3 & -3 & 1 \\ -2 & 1 & 0 \end{bmatrix} A$	
By R ₂ (-1), R ₃ (-1) $\begin{bmatrix} 1 & 2 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} -5 & 3 & 0 \\ -3 & 3 & -1 \\ 2 & -1 & 0 \end{bmatrix} A$	

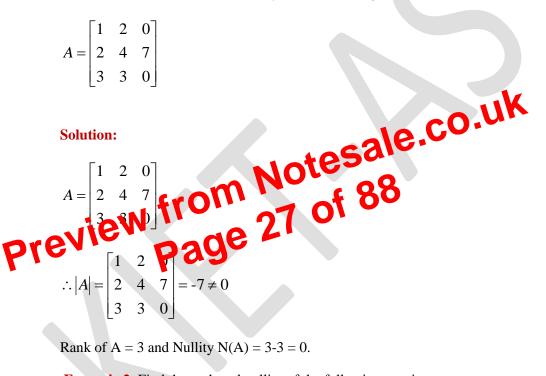
(4) Let A be any matrix (square or rectangular). From this matrix A, delete all columns and rows leaving a certain p columns and p rows. Now if p > 1, then the elements which have been left, constitute a square matrix of order p. The determinant of this square matrix is called a minor of A of order p.

1.13 Nullity of a matrix

Let A be a square matrix of order n and if the rank of A is r, then n-r is called the **nullity of the** matrix A and is usually denoted by N (A).

Thus, Nullity of A i.e. N(A) = Number of column - Rank of A = n-r

Example 1: Find the rank and nullity of the following matrices:



Example 2: Find the rank and nullity of the following matrices:

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 1 & 3 & 5 \\ 2 & 5 & 8 \end{bmatrix}$$

Solution:
$$A = \begin{bmatrix} 1 & 2 & 3 \\ 1 & 3 & 5 \\ 2 & 5 & 8 \end{bmatrix}$$

Determine the rank of the following matrices by reducing to Echelon form:

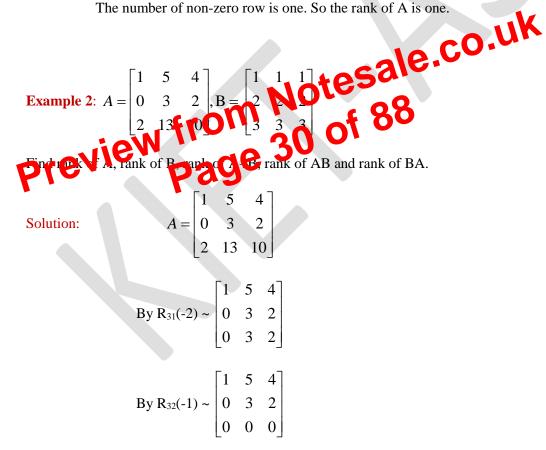
Example 1 : Determine the rank of the following matrices by reducing to Echelon form:

$$A = \begin{bmatrix} 4 & 2 & 3 \\ 8 & 4 & 6 \\ -2 & -1 & -1.5 \end{bmatrix}$$

Solution: Apply elementary row operations on A

By R₂₁(-2), R₃₁(1/2) ~
$$\begin{bmatrix} 4 & 2 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

The number of non-zero row is one. So the rank of A is one.



Rank of A is 2 since the number of non-zero rows is 2.

$$C_{32}(1), C_{42}(-2) \text{post} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 1 & -2 & 1 \end{bmatrix} A \begin{bmatrix} 1 & -3 & -9 & 7 \\ 0 & 1 & 1 & -2 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Thus I₂=PAQ where

$$\mathbf{P} = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 1 & -2 & 1 \end{bmatrix}, \mathbf{Q} = \begin{bmatrix} 1 & -3 & -9 & 7 \\ 0 & 1 & 1 & -2 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}, \text{Rank of } \mathbf{A} = 2.$$

Example 2: Find the non-singular matrices P and Q such that the normal form of A is PAQ where

	1	-1	-1]	
A =	1	1	1	.Hence find the rank
	3	1	1	

Solution: Consider $A_{3X3} = I_{3X3} A_{3X3} I_{3X3}$

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 3 & 1 & 1 \end{bmatrix}$$
. Hence find the rank
Solution: Consider A_{3X3} = I_{3X3} A_{3X3} I_{3X3}

$$\begin{bmatrix} 1 & -1 & -1 \\ 1 & 1 & 1 \\ 3 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ -3 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ -\frac{1}{2} & \frac{1}{2} & 0 \\ -\frac{3}{4} & 0 & \frac{1}{4} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Example 4: Prove that the following equations are consistent and solve 2x+4y-z=9, 3x-y+5z=5, 8x+2y+9z=19.

Solution: The matrix equation AX=B is given by

$$\begin{bmatrix} 2 & 4 & -1 \\ 3 & -1 & 5 \\ 8 & 2 & 9 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 9 \\ 5 \\ 19 \end{bmatrix}$$
(1)
$$\therefore [A:B] = \begin{bmatrix} 2 & 4 & -1:9 \\ 3 & -1 & 5:5 \\ 8 & 2 & 9:19 \end{bmatrix}$$
$$R_{21}(-1), R_{31}(-4) \sim \begin{bmatrix} 2 & 4 & -1:9 \\ 1 & -5 & 6:-4 \\ 0 & -14 & 13:-17 \end{bmatrix}$$
$$R_{12} \sim \begin{bmatrix} 1 & -5 & 6:-4 \\ 2 & 0 & -1:9 \\ 0 & -14 & 13:-17 \end{bmatrix}$$
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$$R_{12} \sim \begin{bmatrix} 1 & -5 & 6:-4 \\ 2 & 0 & -1:9 \\ 0 & -14 & 13:-17 \end{bmatrix}$$
$$R_{32}(1) \sim \begin{bmatrix} 1 & -5 & 6:-4 \\ 0 & 14 & -13 & 0 \\ 0 & -14 & 15:-17 \end{bmatrix}$$
$$R_{32}(1) \sim \begin{bmatrix} 1 & -5 & 6:-4 \\ 0 & 14 & -13:17 \\ 0 & 0 & 0:0 \end{bmatrix}$$
$$R_{2}(\frac{1}{14}) \sim \begin{bmatrix} 1 & -5 & 6:-4 \\ 0 & 14 & -13:17 \\ 0 & 0 & 0:0 \end{bmatrix}$$

which is in Echelon form... Rank of [A:B] = 2 = Rank of A < Number of unknowns.

 \therefore The given equations are consistent and have infinite many solutions. The equations (1) becomes

$$\begin{bmatrix} 1 & -5 & 6 \\ 0 & 1 & -13/4 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} -4 \\ 17/14 \\ 0 \end{bmatrix}$$

$$\therefore x - 5y + 6z = -4, y - (\frac{13}{14})z = \frac{17}{14}.$$

Taking z = k (arbitrary value) $x = (-19k + 29)/14, y = (13k + 17)/14, z = k.$

Example 5:

Prove that what values of λ , μ the equations

 $x + y + z = 6, x + 2y + 3z = 10, x + 2y + \lambda z = \mu$

Have (i) no solution (ii) a unique solution (iii) infinite many solutions.

Solution: The matrix equation AX=B is given by

$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 2 & \lambda \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 6 \\ 10 \\ \mu \end{bmatrix}$$
(1)
$$\therefore \begin{bmatrix} A : B \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 : 6 \\ 1 & 2 & 3 : 10 \\ 1 & 2 & \lambda : \mu \end{bmatrix}$$
(1)
$$R_{21}(-1), R_{32}(-1) \begin{bmatrix} 1 & 1 & 1 & 1 & 1 \\ 1 & 2 & \lambda & 1 & \mu \end{bmatrix}$$
(1)
Note consider the following cross



Hence in this case the equations are consistent and will have a unique solution.

Case II. If $\lambda = 3, \mu = 10$, then Rank of A = Rank of [A:B]= 2 < 3 (Number of unknowns).

Hence in this case the equations are consistent and will have infinite many solutions.

Case III. If $\lambda = 3$, $\mu \neq 10$, then Rank of A = 2, Rank of [A:B]= 3. Therefore, Rank of A \neq Rank of [A:B].

Hence in this case the equations are inconsistent and have no solution.

Example 6:

Prove that what values of λ , μ the equations

 $x + y + z = 1, x + 2y + 4z = \lambda, x + 4y + 10z = \lambda^{2}$

Solution: The given system of equations is homogeneous and hence it is consistent.

Here
$$AX = \begin{bmatrix} 2 & 3 & -1 & -1 \\ 4 & -6 & -2 & 2 \\ -6 & 12 & 3 & -4 \end{bmatrix} \begin{bmatrix} w \\ x \\ y \\ z \end{bmatrix} = 0.$$
 (1)

$$A = \begin{bmatrix} 2 & 3 & -1 & -1 \\ 4 & -6 & -2 & 2 \\ -6 & 12 & 3 & -4 \end{bmatrix}$$

$$R_{21}(-2), R_{31}(3) \sim \begin{bmatrix} 2 & 3 & -1 & -1 \\ 0 & -12 & 0 & 4 \\ 0 & 21 & 0 & -7 \end{bmatrix}$$

$$R_{2}\left(-\frac{1}{4}\right), R_{3}\left(\frac{1}{7}\right) \sim \begin{bmatrix} 2 & 3 & -1 & -1 \\ 0 & -12 & 0 & 4 \\ 0 & 21 & 0 & -7 \end{bmatrix}$$

$$R_{2}\left(-\frac{1}{4}\right), R_{3}\left(\frac{1}{7}\right) \sim \begin{bmatrix} 2 & 3 & -1 & -1 \\ 0 & 3 & 0 & -1 \\ 0 & 3 & 0 & -1 \end{bmatrix}$$

$$Otesale.CO.UK$$
The supernot contains is consistent and solve infinite many solutions.
Here n-rank of A = 4-2=3

Hence arbitrary values will be given to two unknowns.

Now equation (1) becomes
$$AX = \begin{bmatrix} 2 & 3 & -1 & -1 \\ 0 & 3 & 0 & -1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} w \\ x \\ y \\ z \end{bmatrix} = 0.$$

$$\Rightarrow 2w + 3x - y - z = 0, 3x - z = 0$$

-

$$\Rightarrow$$
 If $y = k_1, z = k_2$, then $x = \frac{1}{3}k_2, w = \frac{1}{2}k_1$.

Example 9: Show that the equations :

$$-2x + y + z = a, x - 2y + z = b, x + y - 2z = c.$$

Then geometrically each vector on the line through the origin determined by X gets mapped back onto the same line under multiplication by A. The algebraic eigen value problem consists of determination of such vectors X, known as eigen vectors, such scalars λ , known as eigen values. Thus the finding of non-zero vectors that get mapped into scalar multiples of themselves under a linear operator are most important in the study of vibrations of beams, probability (Markov process), Economics (Leontief model),genetics, quantum mechanics, population dynamics and geometry. For example in a mechanical system, they represent the normal modes of vibration.

Eigen values

If A is a square matrix of order n, we can form the matrix A - λ I. where λ

is a scalar and I is the unit matrix of order n. The determinant of this matrix equated to zero, i.e.,

$$|\mathbf{A} - \lambda I| = \begin{vmatrix} a_{11} - \lambda & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} - \lambda & \dots & a_{2n} \\ \dots & \dots & \dots & \dots \\ a_{n1} & a_{n2} & \dots & a_{nn} - \lambda \end{vmatrix} = 0 \quad \text{is called the characteristic equation of A.}$$

equation of degree n in

$$\lambda$$
 of the form $(-1)^n \lambda^n + k_1 \lambda^{n-1} + k_2 \lambda^{n-1} + k_2 \lambda^{n-1} + k_3 = 38$
The roots of this equation are called **characteristic roots or latent roots or eigenvalues of A**.

Consider the linear transformation Y = AX

that transforms the column vector X into the column vector Y. In practice, we are often required to find those vectors X which transform into scalar multiples of themselves.

Let X be such a vector which transforms into $\lambda X(\lambda \text{ being a non - zero scalar})$

According to the transformation (1).

Then $Y = \lambda X$

(2)

(1)

From (1) and (2), $AX = \lambda X \Longrightarrow AX - \lambda IX = 0 \Longrightarrow (A - \lambda I)X = 0$ (3)

This matrix equation gives n homogeneous linear equations

$$\begin{array}{c}
(a_{11} - \lambda)x_1 + a_{12}x_2 + \dots + a_{1n}x_n = 0 \\
a_{21}x_1 + (a_{22} - \lambda)x_2 + \dots + a_{2n}x_n = 0 \\
\dots \\
a_{n1}x_1 + a_{n2}x_2 + \dots + (a_{nn} - \lambda)x_n = 0
\end{array}$$
(4)

These equations will have a non-trivial solution only if the co-efficient matrix (5)

$$\begin{vmatrix} 3-\lambda & 1 & 4 \\ 0 & 2-\lambda & 6 \\ 0 & 0 & 5-\lambda \end{vmatrix} = 0 \Rightarrow (3-\lambda)(2-\lambda)(5-\lambda) = 0 \Rightarrow \lambda = 2,3,5 \\ The eigen vector corresponding to eigen value $\lambda = 2$ is given by $(A-\lambda I)X_1 = 0 \Rightarrow (A-2I)X_1 = 0$

$$\Rightarrow \begin{bmatrix} 3-2 & 1 & 4 \\ 0 & 2-2 & 6 \\ 0 & 0 & 5-2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0 \text{ or } \begin{bmatrix} 1 & 1 & 4 \\ 0 & 0 & 6 \\ 0 & 0 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0$$

$$R_{23}(-2) \sim \begin{bmatrix} 1 & 1 & 4 \\ 0 & 0 & 6 \\ 0 & 0 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0$$

$$R_{23} \sim \begin{bmatrix} 1 & 1 & 4 \\ 0 & 0 & 3 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0$$

$$\therefore x_1 + x_2 + 4x_3 = 0, 3x_3 = 0 \text{ or } x_3 = 0. \therefore x_2 = -x$$

$$\therefore X_1 = \begin{bmatrix} 1 \\ -1 \\ 0 \\ 0 & 2-3 & 6 \\ 0 & 0 & 5-3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0 \text{ or } \begin{bmatrix} 0 & 1 & 4 \\ 0 & -1 & 6 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0$$

$$\therefore x_2 + 4x_3 = 0, -x_2 + 6x_3 = 0, 2x_3 = 0.$$
Solving these equations, we have
 $x_3 = 0, x_2 = 0, x_1 = 1(say)$

$$\therefore X_2 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \text{ is the eigen vector for } \lambda = 3.$$
The eigen vector corresponding to eigen value $\lambda = 5$ is given by
 $(A - \lambda I)X_3 = 0 \Rightarrow (A - 5I)X_3 = 0$

$$\Rightarrow \begin{bmatrix} 3-5 & 1 & 4 \\ 0 & 2-5 & 6 \\ 0 & 0 & 5-5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0 \text{ or } \begin{bmatrix} -2 & 1 & 4 \\ 0 - 3 & 6 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0$$$$

$$\Rightarrow \begin{vmatrix} 2-\lambda & 1 & 1\\ 0 & 1-\lambda & 0\\ 1 & 1 & 2-\lambda \end{vmatrix} = 0$$

On simplification, $\lambda^3 - 5\lambda^2 + 7\lambda - 3 = 0$

Now, to verify Cayley-Hamilton theorem we have to show that

$$A^3 - 5A^2 + 7A - 3I = 0 \tag{1}$$

For A^{-1} , Pre multiplying equation 1) by A^{-1}

$$A^{-1}(A^{3} - 5A^{2} + 7A - 3I) = A^{-1}O$$

$$\Rightarrow A^{2} - 5A + 7I - 3A^{-1} = O$$

$$\Rightarrow 3A^{-1} = A^{2} - 5A + 7I$$
(2)
Now, $A^{2} = A \cdot A = \begin{bmatrix} 2 & 1 & 1 \\ 0 & 1 & 0 \\ 1 & 1 & 2 \end{bmatrix} \begin{bmatrix} 2 & 1 & 1 \\ 0 & 1 & 0 \\ 1 & 1 & 2 \end{bmatrix} \begin{bmatrix} 2 & 1 & 1 \\ 0 & 1 & 0 \\ 1 & 1 & 2 \end{bmatrix} = \begin{bmatrix} 5 & 4 & 4 \\ 0 & 4 & 4 & 5 \end{bmatrix}$
From equation (2), $3A^{-1} = \begin{bmatrix} 5 & 4 & 4 \\ 0 & 1 & 0 \\ 4 & 4 & 5 \end{bmatrix} - 5\begin{bmatrix} 2 & 1 & 1 \\ 0 & 1 & 0 \\ 4 & 4 & 5 \end{bmatrix} + \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 7 \end{bmatrix} = \begin{bmatrix} 2 & -1 & -1 \\ 0 & 3 & 0 \\ -1 & -1 & 2 \end{bmatrix}$

$$\Rightarrow A^{-1} = \frac{1}{3} \begin{bmatrix} 2 & -1 & -1 \\ 0 & 3 & 0 \\ -1 & -1 & 2 \end{bmatrix}$$
Now, $A^{8} - 5A^{7} + 7A^{6} - 3A^{5} + A^{4} - 5A^{3} + 8A^{2} - 2A + I$

$$= A^{5}(A^{3} - 5A^{2} + 7A - 3I) + A^{4} - 5A^{3} + 8A^{2} - 2A + I$$

$$= A^{5}(A^{3} - 5A^{2} + 7A - 3I) + A^{2} + A + I$$

$$= A(A^{3} - 5A^{2} + 7A - 3I) + A^{2} + A + I$$

$$= A(A^{3} - 5A^{2} + 7A - 3I) + A^{2} + A + I$$

$$= A(A^{3} - 5A^{2} + 7A - 3I) + A^{2} + A + I$$

$$= A(A^{3} - 5A^{2} + 7A - 3I) + A^{2} + A + I$$

The modal matrix of A is
$$M = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ -1 & -1 & 0 \end{bmatrix}$$

And
$$D = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

Now we have to find M^{-1} :

$$M \sim I$$

$$\begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ -1 & -1 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} , R_3 \rightarrow R_3 + R_1$$

$$\Rightarrow \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & -1 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} , R_3 \rightarrow R_3 + R_2$$

$$\Rightarrow \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 2 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix} , R_3 \rightarrow R_3 + R_2$$

$$\Rightarrow \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 2 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix} , R_1 \rightarrow R_1 - R_3, R_2 \rightarrow R_2 - R_3$$

$$\Rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \sim \begin{bmatrix} \frac{1}{2} & \frac{-1}{2} & \frac{-1}{2} \\ -\frac{1}{2} & \frac{1}{2} & \frac{-1}{2} \\ \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{bmatrix}$$

$$\Rightarrow M^{-1} = \begin{bmatrix} \frac{1}{2} & \frac{-1}{2} & \frac{-1}{2} \\ -\frac{1}{2} & \frac{1}{2} & \frac{-1}{2} \\ -\frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & -1 & -1 \\ -1 & 1 & -1 \\ 1 & 1 & 1 \end{bmatrix}$$

We know that, $M^{-1}AM = D$

Pre multiplying equation (α) by *M* and post multiplying by M^{-1}

$$M(M^{-1}AM)M^{-1} = MDM^{-1}$$